



Cutes Corporation

CT-2000_{PLUS/PRO} Series
AC MOTOR DRIVER

Instruction

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Introduction

Thank you for choosing the CT-2000Plus/Pro inverter unit, this inverter unit is suitable for operating squirrel cage induction motors. Please read this instruction manual carefully before actual usage in order to ensure proper operation and suit your needs.

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1. Inspection upon receiving

- A. Check that the model, the capacity and power voltage specifications are as ordered.
- B. Check that no damage has occurred during transportation.
- C. Check that none of the internal parts have been damaged or have fallen off.
- D. Check that none of the connectors have been damaged or have fallen off.
- E. Check that there is no loosening of the terminals or screws of each of the parts.

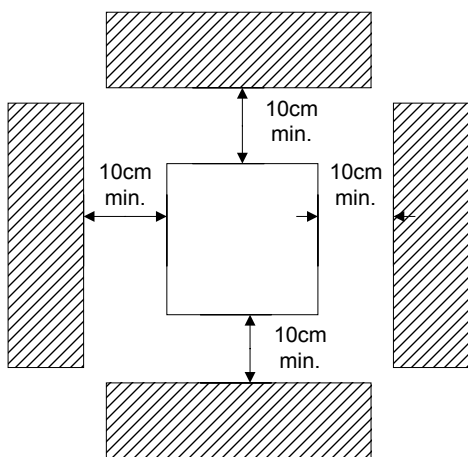
2. Installation and Storage

A. Storage:

If the equipment is not to be installed immediately, it should be stored in a clean and dry location at ambient temperatures from 20 to 55 . The surrounding air must be free of corrosive contaminants.

B. Installation place:

Places where the peripheral temperature is from -10 to 40 , and where the relative humidity is 90% or less. Avoid installing at places where there is dust, iron particles, corrosive gas, water spray, direct sunlight or too much vibration. And places where has good ventilation.



3. Application notes

A. Concerning the inverter unit

- (1) Do not fit capacitors to the output side of the inverter in order to improve the power ratio.
- (2) In case of fitting MC between inverter and motor to control motor operation, then the capacity of inverter must be 6 times the capacity of motor.
- (3) Run a motor that is within the capacity of the inverter unit, light load current and no-load current will cause the motor to develop ripple current.
- (4) This unit is provided with a current limiting function. The starting torque is assumed to be from 80% to 100%.

B. Concerning the AC motor

- (1) When general-purpose motors are operated at low speeds, there is a reduced cooling effect, please apply the special purpose motor.
- (2) Operation at frequencies exceeding 60 Hz requires caution, as there is the danger of the mechanical strength failure of the motor.
- (3) When motors with brakes are being operated, the power for the brake and inverter should be taken from the same power supply and the brake operation must be in phase when the unit is started and stopped.

4. Block diagram and Wiring

A. Wiring of main and control circuit

Wire according to the standard connection diagram. On using the external sequence control, please use small signal relay or double terminal relay to avoid relay terminal malfunction.

B. Signal circuit

The signal circuit uses either shielded pairs or twisted pairs, should be wired either using a wiring duct separated from that for the power circuit, or with the wiring conduit isolated as much as possible.

Block diagram, wiring

C. Connecting the power supply and the AC motor

Connect the main circuit, by wiring according to the main circuit terminal connection diagram. Care is required not to make a mistake when connecting the input and output terminals, lest it will cause inverter damage. Specifications of main circuit path and NFB are as follow:

Voltage (V)	Model	NFB (A)	Wire size for circuit (mm ²)
220	2	10A	2~5.5
	3	15A	3.5~5.5
	5	20A	5.5
	7.5	30A	5.5~8
	10	40A	5.5~8
	15	60A	22
	20	80A	30
	30	120A	38
	40	150A	38~100
	50	200A	38~100
	60	250A	60~100
	75	300A	100
	100	400A	100~200
	125	500A	100~200
380 440	2	5A	2~5.5
	3	7.5A	2~5.5
	5	10A	3.5~5.5
	7.5	15A	3.5~5.5
	10	20A	5.5
	15	30A	8~14
	20	40A	8~14
	30	60A	22
	40	80A	22
	50	100A	30
	60	120A	50
	75	150A	38~100
	100	200A	38~100
	125	250A	60~100
150	300A	100	

D. R.S.T. for Power source reactor

Instantaneous current and to improve power ratio, it should be fitted the A.C.L. to R.S.T. input side under the following circumstance:

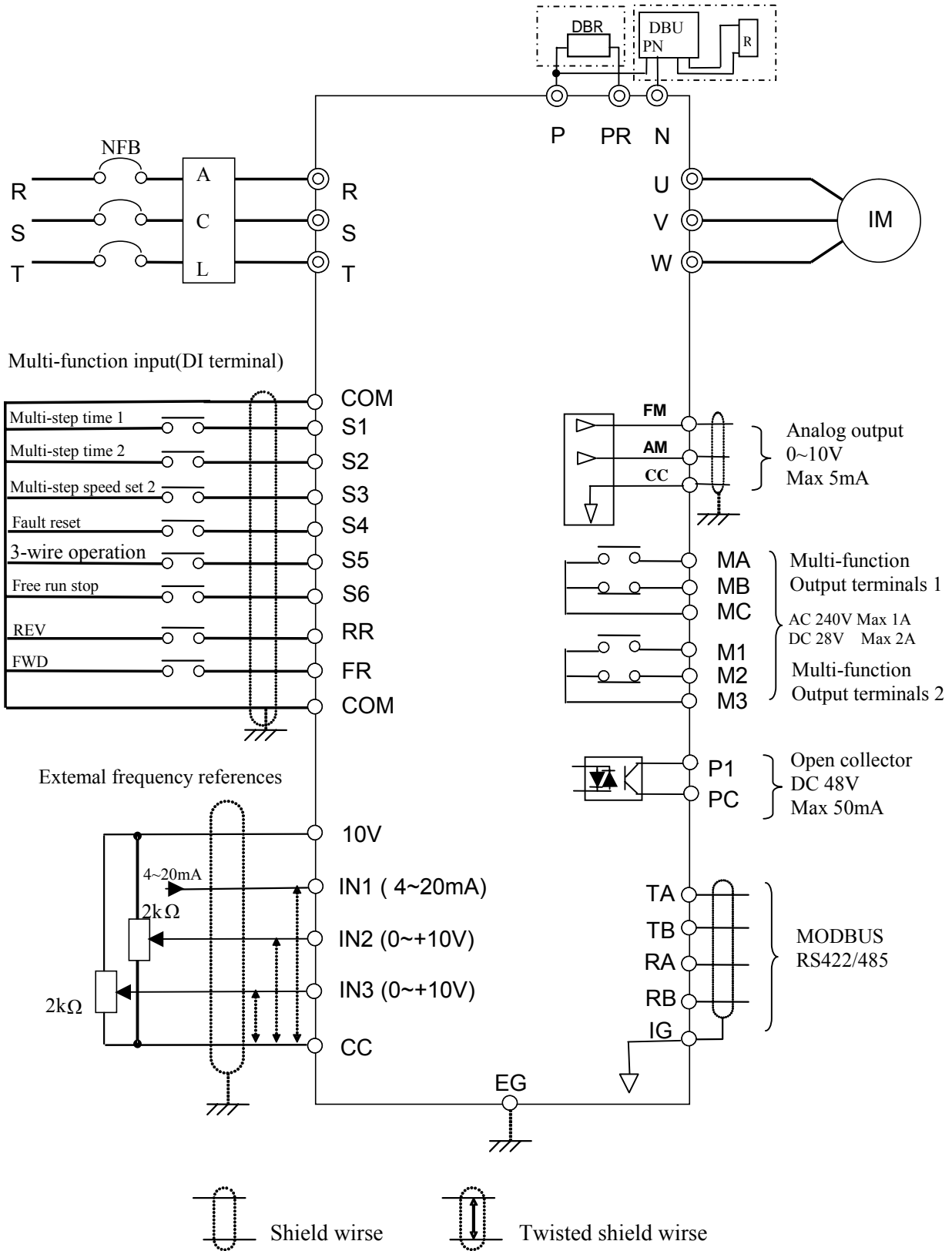
- a. Where power supply capacity is larger than 500 KVA.
- b. Using thyrister, phase advance capacitor etc. from the same power supply.

A.C.L. Specifications table:

Voltage (V)	HP	Current (Ar.m.s)	Induction Value
220	2	10A	1.1mH
	3	15A	0.71mH
	5	20A	0.53mH
	7.5	30A	0.35mH
	10	40A	0.26mH
	15	60A	0.18mH
	20	80A	0.13mH
	30	120A	0.09mH
	40	150A	70uH
	50	200A	50uH
	60	250A	44uH
	75	300A	35uH
	100	400A	27uH
	125	500A	21uH
380 440	2	5A	4.2mH
	3	7.5A	3.6mH
	5	10A	2.2mH
	7.5	15A	1.42mH
	10	20A	1.0mH
	15	30A	0.7mH
	20	40A	0.53mH
	30	60A	0.36mH
	40	80A	0.26mH
	50	100A	0.21mH
	60	120A	0.18mH
	75	150A	0.14mH
	100	200A	0.11mH
	125	250A	0.10mH
150	300A	70uH	

Notes: The A.C.L. for 220V and 380V/460V have different induction values, please does not mix up.

E. Standard External Connection Diagram



F. Terminal Specifications

Classification	Terminal symbol	Terminal name	Specification
Main Circuit	R.S.T	AC power input terminal	3ΦAC 200~240V 50/60HZ 3ΦAC 380~460V 50/60HZ
	U.V.W	Inverter output terminal	3-phase induction motor
	E	Ground Terminal	Ground Terminal of inverter
	P、PR	Breaking unit connecting terminal	Connected with brake unit (DBU)
	P、N	Breaking resistor connecting terminal	Connected with brake unit DBU
Analog input/output terminal	10V	+10V power outout	Provide +10VDC 30mA power
	CC	Common of analog input/ output	Common of analog input/ output terminal
	IN1	Multi-function analog input 1	4~20mA input
	IN2	Multi-function analog input 2	0~10V input
	IN3	Main speed analog input 3	0~10V input
	FM	Multi-function analog output	0~10V 5mA output
	AM		
Multi-function analog input terminal	S1	2 nd acceleration input terminal (AC2)	Select 2 nd acceleration time mode by shorting 1-COM, set CD10
	S2	2 nd deceleration input terminal (DC2)	Select 2 nd deceleration time mode by shorting 2-COM, set CD11
	S3	3 rd speed input terminal (3DF)	Select 3 rd operation speed by shorting 3-COM, frequency is set by CD13
	S4	Jogging operation or 5 th speed (JOG/5DF)	Shorting 4-COM, JOG/5DF is set by CD59
	S5	2 nd speed input terminal (2DF)	Select 2 nd operation speed by shorting 5-COM, frequency is by CD12
	S6	Free-run operation or alarm reset (MBS/RST)	Shorting 6-COM, MBS/RST is set by CD59
	COM	Concurrent of multi-function input terminal	Contact and operation control terminal COM common
Operation control terminal	RR	reverse / stop terminal	ON: reverse , OFF: stop
	FR	forward / stop terminal	ON: forward , OFF: stop
	COM	Operation control terminal	Multi-function input and Operation control terminal common
Multi-function analog output contact	MA、M1	Multi-function output contact A	240VAC Max 1A 28VDC Max 10A
	MB、M2	Multi-function output contact B	
	MC、M3	Multi-function output contact concurrent	
MODBUS Communication terminal	TA	RS422 T+	RS422 T+ or RS485 + terminal
	TB	RS422 T-	RS422 T- or RS485 - terminal
	RA	RS422 R+	RS422 R+
	RB	RS422 R-	RS422 R-
	IG	Shield grounding terminal	Provide shield grounding system 0V
Open-collector output common	P1	Multifunction output connector	Below DC 48V 50mA
	PC	Multifunction output connector common	
Grounding terminal	EG	Shield grounding terminal	Offer shield grounding, applied for analog and input terminal

5. Operational Test

A. Check before test

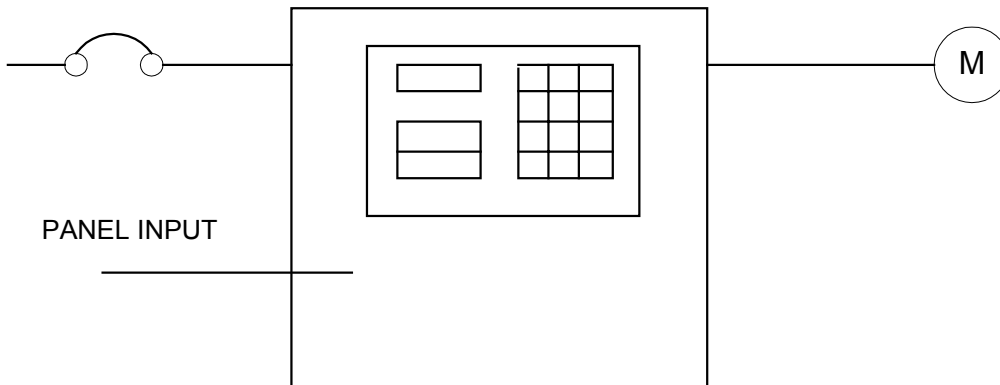
Please check the following:

- (1) Is wiring correct? Check especially the input and output terminals.
- (2) Is there a short-circuit or ground connection on external wiring?
- (3) Make sure there is no loosening of screws.
- (4) Check external sequence control circuit.
- (5) Check voltage of power supply.

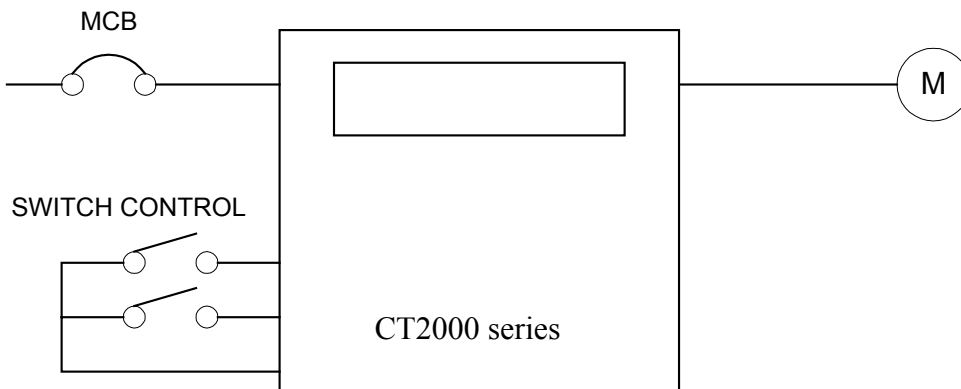
B. Operation Method

CT-2000 series inverter unit has both operator panel and external operation methods.

(1) Operator panel



(2) External signal operation



C. Operational test

Test according to the following procedure and be aware of indications.

(1) Basic operational test

-Operational procedure

- I. Connect power supply
- II. Monitor glittering indicates frequency
- III. Press either FWD or REV key, motor starts running. It will stop accelerating after reaching set frequency
- IV. After pressing STOP key, motor stops and indicating frequency steps down. The set frequency starts glittering after the motor stops.
- V. Repeat procedures III and IV to test forward and reverse operations.

-Operation monitor display

- I. STOP display, with reciprocal glittering indicated HZ LED and factory setting 10.00HZ.
- II. Hz display, with FWD (or REV) LED lighted up steadily; indication goes up according to frequency until reaching value 10.00 Hz
- III. Indication goes down according to operation frequency, and returns to situation " I " after stop

(2) Frequency change test

- Operational procedure

- I. Exercise the above operation test procedures I, II, III
- II. Adjust VR on the panel to change frequency command
- III. Repeat procedures II to increase or decrease frequency

-Operation monitor display

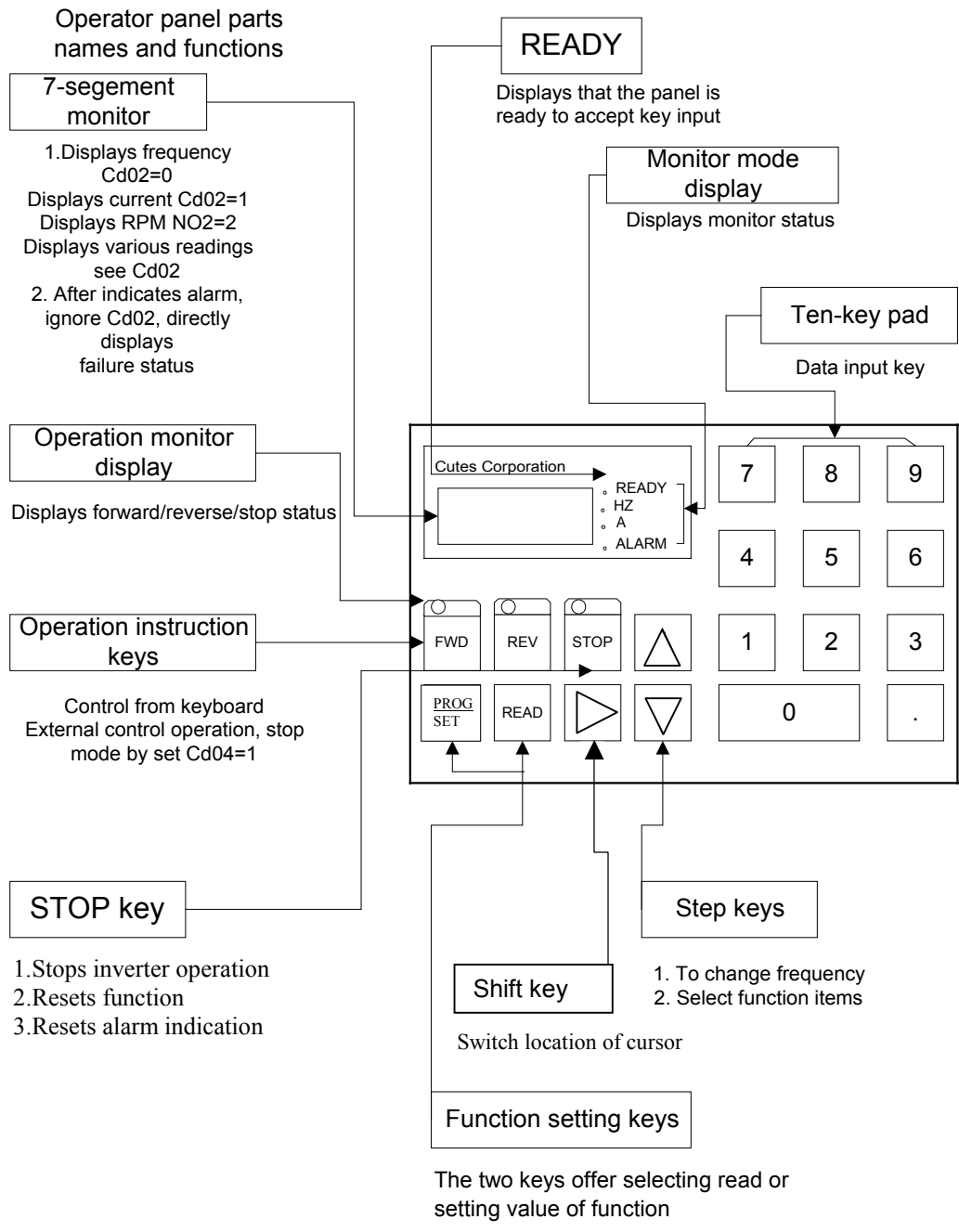
- I. The same as the above basic test of I, II
- II. Monitor display indicates the current new setting value

Note:

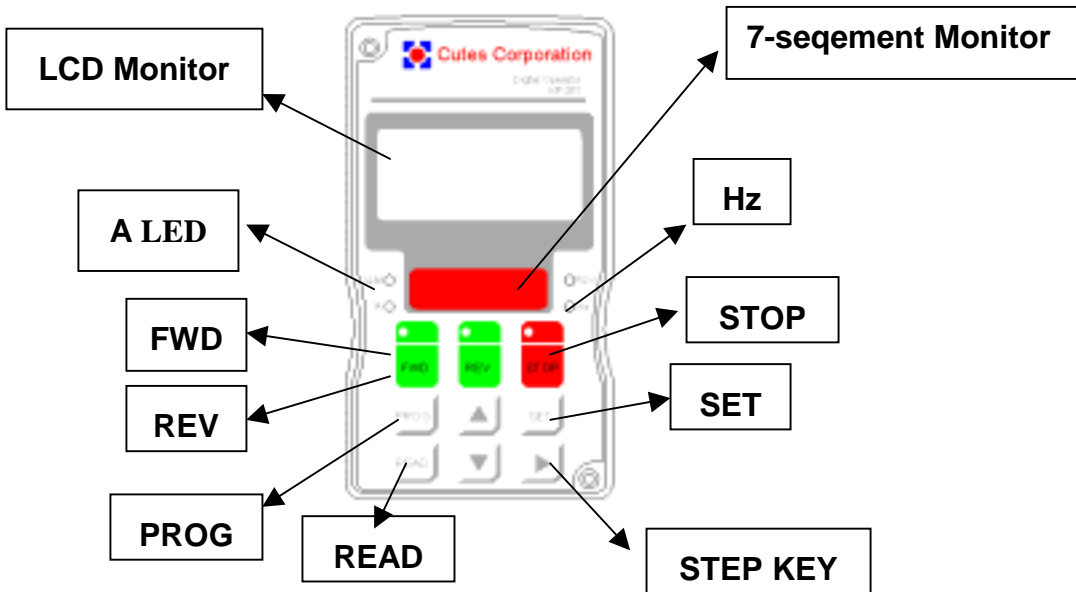
1. Is motor operation direction correct? (Changing any two of U.V.W output terminals to change motor operation direction)
2. Is there any noise or vibration on motor?
3. Is it run smoothly during acceleration and deceleration?
4. Is there any power failure?

6. Adjust and Function Specification

A. Keypad operation



B. LCD Keypad Adjust and Function Specification



C. Display specification

LED	Display specification
RDY	RDY LED means the Keyboard working normally.
HZ	HZ LED means of recent revolution frequency.
A	A LED means of recent revolution current.
FWD	FWD LED means motor operate at forward direction.
REV	REV LED means motor operate at reverse direction.
STOP	STOP LED means motor operate at stop.

D. Keyboard specification

Bottom	Function	Bottom specification
FWD	MOTOR RUN	Push keypad to control forward of motor, and screen display main display content (Cd02 setting).
REV	MOTOR RUN	Push keypad to control reverse of motor, and screen display main display content (Cd02 setting).
STOP	STOP	Stop motor revolution when push STOP key, and on the mean time screen flashing with commanding instruction.
	RESET	While failure occurred, press STOP key to re-start inverter and save failure in failure memory.

Adjust and Function Specification


<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: auto;">PROG</div>	SELECT FUNCTION	In display mode, press PROG key and screen shows Cd00 (General parameter input area). Press PROG/SET key again and screen shows CE00 (failure and engineering mode). If pressed PROG/SET key now, screen would return to display mode.
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: auto;">READ</div>	READ	When display shows Cd (General parameter Input mode) or CE (Failure display and engineering mode), Press READ to parameter input mode. Screen showing previously parameter setting. Change of parameter can be proceeding.
	CANCEL	Press READ at parameter input mode can escape from parameter input mode and not save new parameter.
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: auto;">SET</div>	SET and SAVE	In parameter input mode, press SET key will save new parameter just input.
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: auto; margin-bottom: 5px;">□</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: auto; margin-bottom: 5px;">□</div>	Item of display changing	Press , key at display mode, select required item.
	Parameter selection	Press , key to change value when screen shows Cd (General parameter input area) or CE (Failure display and engineering mode). Press and hold , key can progressively increase or decrease value.
	Parameter modification	Press , key at parameter input mode can change parameter. Using with SET key to modify parameter.
<div style="text-align: center;">▶ (show as >)</div>	SHIFT	Press > key to switch location of cursor. If press > key again when cursor is at right end side, it will return to left side. Parameter can be changed by using this key with , key.
<div style="border: 1px solid black; padding: 2px; width: fit-content; margin: auto; margin-bottom: 5px;">0</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: auto; margin-bottom: 5px;">9</div> <div style="border: 1px solid black; padding: 2px; width: fit-content; margin: auto;">□</div>	Input a number	Input a number

E. Function Code

If you see this symbol @ in each parameter descriptions which means that the LCD display as an error, but the parameters are still this feature. (The next version of the keyboard's LCD will display the correct text.)

§Cd00 Set frequency (setting range 0-400 HZ)

There are 5 methods to change set frequency. Items A~C are methods of panel key operation, items D-E are methods of external terminal input.

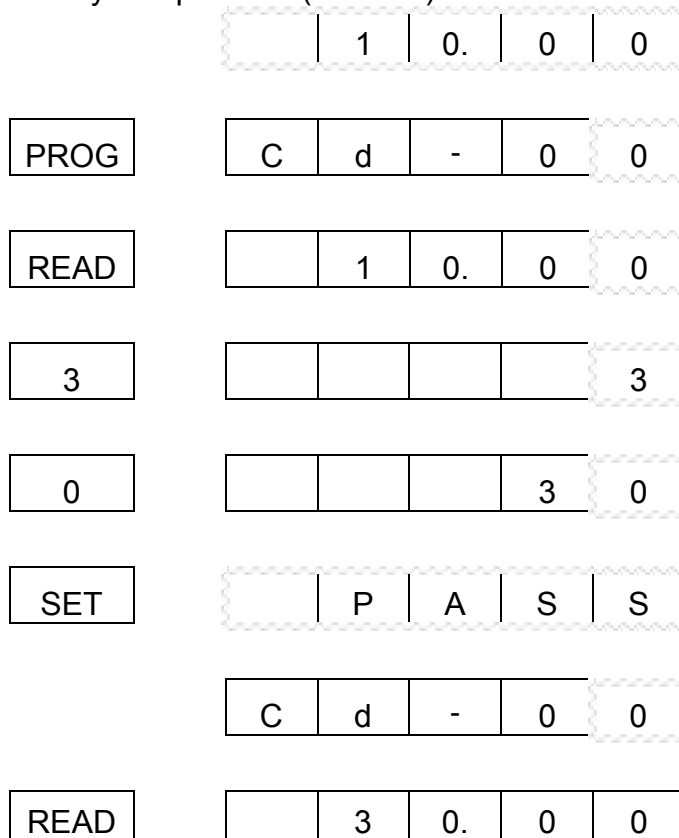
- A. Use PROG key to input data (Cd01=0)
- B. Use  key to input data (Cd01=0)
- C. Use Multi-Step function to setting (Refer to function CE05 to CE55.)
- D. Set external voltage
- E. Set external current


Note:

1. Set value should be in accordance with V/F slope (Cd05) and upper limit frequency (Cd17).

Set by function key

- A. Use PROG key to input data (Cd01=0)



Note : , Indicate 7 Segment LED flash.

§Cd01 Setting procedure of frequency (Setting range 0-7)

The function cannot be modified during operation.

Setting procedure of frequency is to select either panel key or external analog signal.

- Cd01=0 Set frequency on operation panel, as the above items A-C.
- Cd01=1 Set frequency by terminal In2 DC 0-10V/5KΩVR
- Cd01=2 Set frequency by terminal In1 DC 4-20mA
- Cd01=3 Set frequency by terminal In2+IN3 DC 0-10V/5KΩVR
- Cd01=4 Setting from terminal In2, input DC0 10V/VR 5KΩ hysteresis
- Cd01=5 Setting from terminal In1, input DC4 20mA hysteresis
- Cd01=6 Setting from terminal In2+IN3, input DC0 10V/VR 5KΩ hysteresis
- Cd01=7 Set frequency by Multi-step function mode

§Cd02 Select Main monitor display (Setting range 0-15)

The monitor is consisted of four 7-segment LEDs, displays frequency, current and various data by digital number and character.

- Cd02=0 Display the frequency, LED HZ active
- Cd02=1 Display the current, LED I active
- Cd02=2 Display Ultimate speed, Hz and I LED de-active.
- Cd02=3 Display DC current of DC BUS, showing d in front of value
- Cd02=4 Display rms value of U.V.W. AC output , LED HZ, I active
- Cd02=5 Display external control terminal status, showing E in front of value
- Cd02=6 Display temperature rising of PIM module, showing H in front of value
- Cd02=7 Display speed feedback. Check if MCK circuit working properly, then the restart and free run start function (Cd28) will working normally.
- Cd02=8 Display average speed of multi-step function (rpm)
- Cd02=9 Display current step of multi-step function (step)
- Cd02=10 Display current time of multi-step function (minutes)
- Cd02=11 Display Yards counter value
- Cd02=12 Display power factor (cos Θ)
- Cd02=13 Display instant power (KW)
- Cd02=14 Display KW-h
- Cd02=15 Display MW-h

§Cd03 Torque mode (Setting range 0-1)

The function cannot be modified during operation.

- Cd03=0 Automatic torque compensation de-active, set compensation by Cd07.
- Cd03=1 Initial Torque boost active, Maximum boost is 1.5 * Cd07 setting value. Start boost while operation frequency greater than 3 Hz.
- Cd03=2 Initial Torque boost active, Maximum boost is 1.5 * Cd07 setting value. Start boost while operation frequency greater than 1.5 Hz.

§Cd04 Operation command mode (Setting range 0-1)

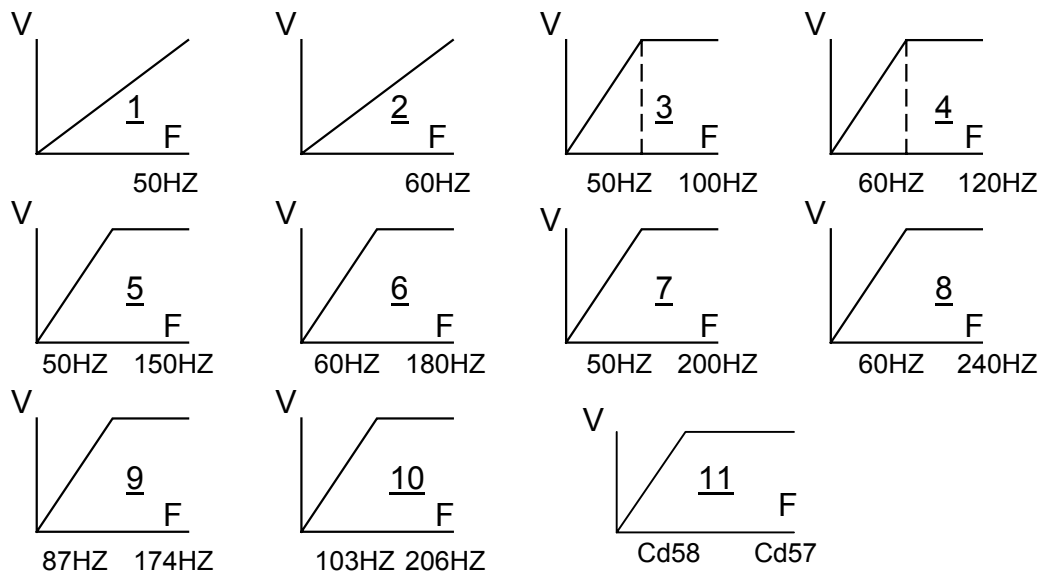
The function cannot be modified during operation.

- Cd04=0 Operation on operation panel
- Cd04=1 Operation by external terminal, including FR, RR, common terminal (1, 2, 3, 4, 5, 6)

§Cd05 Set V/F pattern (Setting range 1-11)

The function cannot be modified during operation.

There are 11 patterns of V/F slope, as follow:



When Cd05=11, V/F slope is determined by Cd57, Cd58.

§Cd06 Motor current rate (Setting range 25-100)

Set motor overload protective current, in order to avoid motor failure because of overload. Set value=100, please calculate the following formula:

Set Value = Motor rated current / Inverter rated current × 100

Ex. Use inverter with 3.7KW(5HP) to drive motor with 2.2KW(3HP)

Inverter rated current = 17.4A

Motor rated current = 8A

Set Value = 8 / 17.4 × 100 = 46%

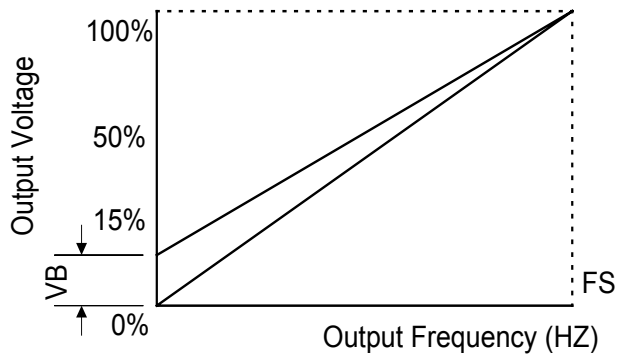
Adjust and Function Specification

§Cd07 Torque compensation Vb (Setting range 0-15)

The function cannot be modified during operation.

This function is to raise output voltage to increase torque of motor.

It can also be used to increase load slope of low voltage produced by long wiring between inverter and motor, as well as fluid, fan and pump.



§Cd08, 09, 10, 11 Acceleration/deceleration time (Setting range 0-6000)

The time needed for set frequency from 0Hz to 50Hz.

There are 2 selections for each of acceleration time and deceleration time.

To set acceleration/deceleration time

$$\text{Set Value (T)} = (50 - 0) / F \times T1$$

T1: time needed for accelerate / decelerate

F: frequency changed

Ex.: Frequency from 50Hz down to 30Hz, needed time 1 sec. Then:

$$\text{Set Value (T)} = 50 / 50 - 30 \times 1 = 2.5$$

Cd08 = Acceleration time

Cd09 = Deceleration time

Cd10 = 2nd Acceleration time

Cd11 = 2nd Deceleration time

Note: The 2nd acceleration / deceleration time only available on external operation mode.

(e.g. Cd04=1)

§Cd12, 13, 14 Speed setting (Setting range 0-400)

This function has 4 kinds of speed setting

The 2nd, 3rd, 4th speeds are set from external terminal FR (or RR) which accommodate terminal 3, 5, the setting value cannot exceed the allowed range.

Cd12 = 2nd speed setting

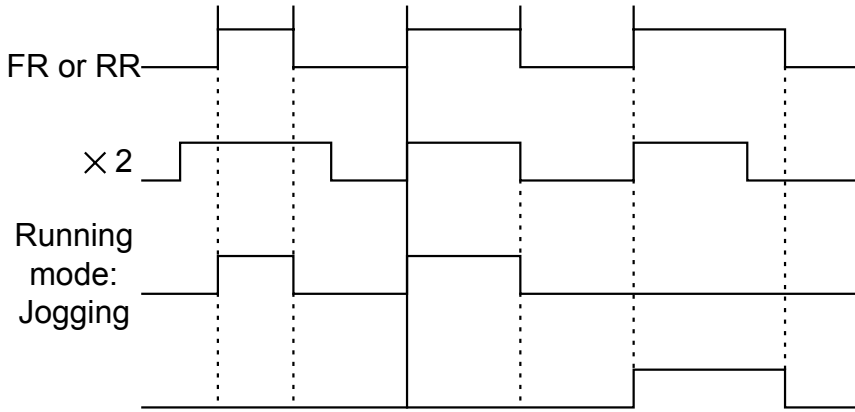
Cd13 = 3rd speed setting

Cd14 = 4th speed setting

Note: When apply to multi-speed setting, use external control (e.g. Cd04=1) to start and use panel to pre-input to set frequency.

§Cd15 Jogging frequency (Setting range 0-60)

To control jogging, use external terminal 4-FR or 4-RR with COM shorted.
Set running direction



Forward(Reverse)

Note: Jogging operation is valid only when operation command selects the external operation signal mode (e.g. Cd04=1) and Cd59=0 or 1.

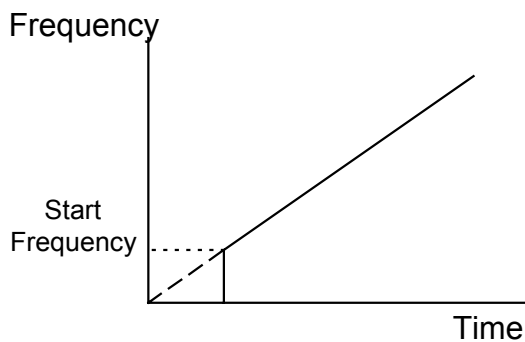
Jogging operation procedures:

1. First put in 4, and then FR (or RR).
 2. Put in 4 and FR (or RR) simultaneously.
- Be sure always to put in 4 before FR (or RR).

§Cd16 Start frequency (Setting range 0.5-60)

Set motor start frequency

Setting range of frequency from 0.5Hz to 30Hz, accuracy is 0.01Hz.



Note: The most appropriate range for start frequency is 0.5Hz to 10Hz.

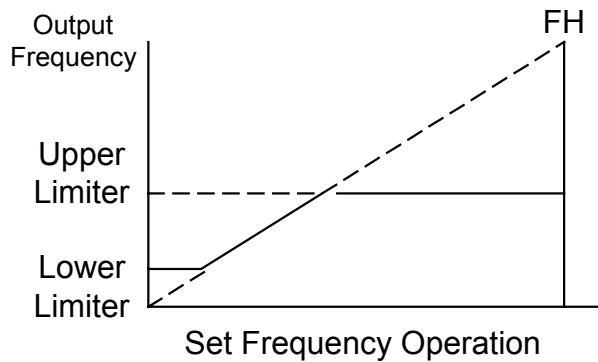
§ Cd17 Upper limiter of frequency (Setting range 10-400)

This limiter is used to operate within upper limit frequency of motor
Avoid input errors caused by the panel keys and result in mechanical damage.

Adjust and Function Specification

§Cd18 Lower limiter of frequency (Setting range 0-100)

This limiter is used to operate within lower limit frequency of motor



§Cd19 Acceleration / deceleration time of jogging (Setting range 0-600)

Time needed for set frequency from 0Hz to 50Hz.

$$\text{Set Value (T)} = (50 - 0) / F \times T1$$

T1: Time needed for acceleration/deceleration

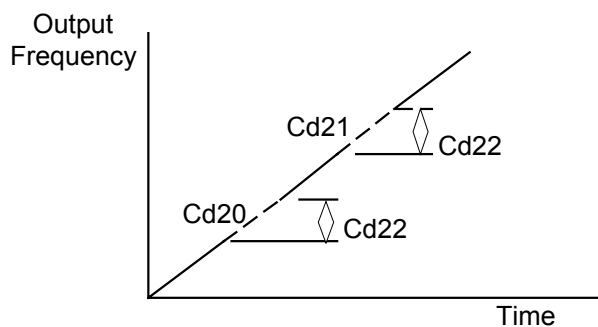
F: Frequency changed

§Cd20, 21 Jump frequency (Setting range 0-400)

This function is to avoid mechanical resonance frequency

Frequency operation automatically jumps to point +/- jump width (set by Cd22)

This function is only available on constant speed operation, not influence during acceleration/deceleration, it is settable at 2 points.



§Cd22 Jump frequency width (Setting range 0-6)

This function must accommodate Cd20 and Cd21

§Cd23 Braking mode (Setting range 0-3)

This function must accommodate Cd24, Cd25, and Cd26.

Cd23=0 No DC braking

Cd23=1 Stop mode

Cd23=2 Start mode

Cd23=3 Stop and start mode

§Cd24 DC braking frequency (Setting range 1-20)

This function must accommodate Cd23, Cd25, and Cd26.

Set frequency of DC brake starts at the time of inverter deceleration stops, the DC brake is active when operates below the starting frequency.

§Cd25 DC braking voltage (Setting range 0-100)

This function must accommodate Cd23, CD24, and Cd26.

DC braking torque setting

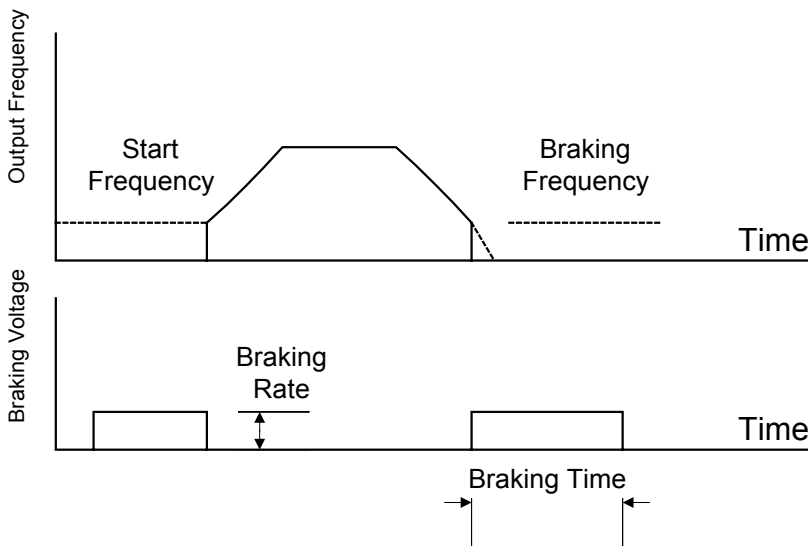
When DC brake is active, monitor displays “dCbr”

Cd25=0-100, the higher value the higher output brake torque

Note: When DC brake voltage is high, be aware of over current.

§Cd26 DC braking time (Setting range 1-60)

Adjust DC braking time



Note:

1. DC braking time too long or too many times is possible to cause motor damage because of overheating.
2. Set Cd23=0 when DC braking is not required.

Adjust and Function Specification

§Cd27 Run direction (Setting range 0-1)

Use operation control terminal to execute operation. No keypad stop (STOP)。

Cd27=0 to execute reverse by keypad (REV)。

Cd27=1 unable to execute reverse by keypad (REV)

Notice : Cd27 prohibits reverse selecting, only restricts keypad control.

§Cd28@ Speed search selection (Setting range 0-3)

§CE64@ Speed search current (Setting range 0-200)

§CE65@ Speed search deceleration time (Setting range 0.1-10)

§CE66@ Speed search waiting time (Setting range 0-20)

The speed search function finds the actual speed of motor that is Rotational using inertia, and then starts smoothly from that speed. When restoring power after a temporary power loss or Rotational using inertia fan is enable. There are two ways of speed search by set Cd28.

Cd28= 0, invalid

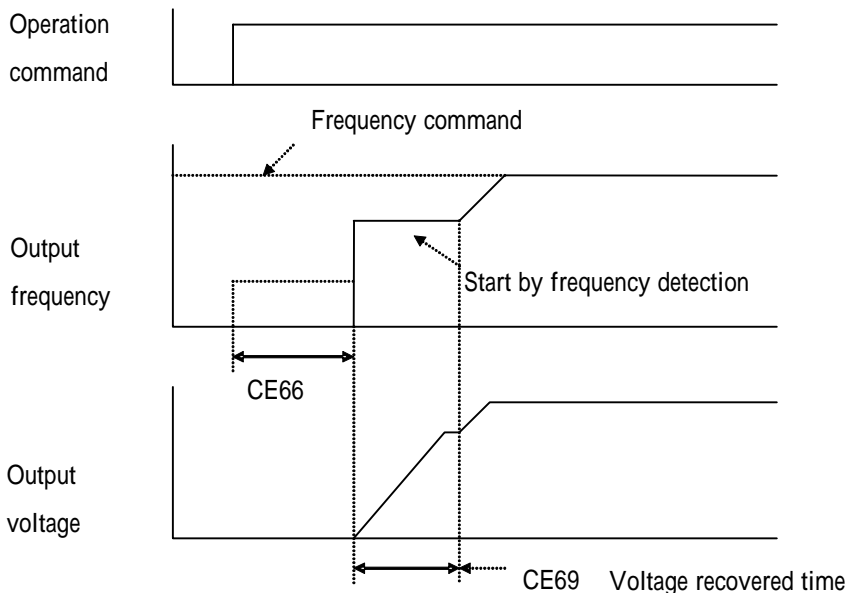
= 1, valid, MCK feedback (above 3HP)

= 2, valid, current detection

= 3, valid, MCK disconnection start+ inertia start

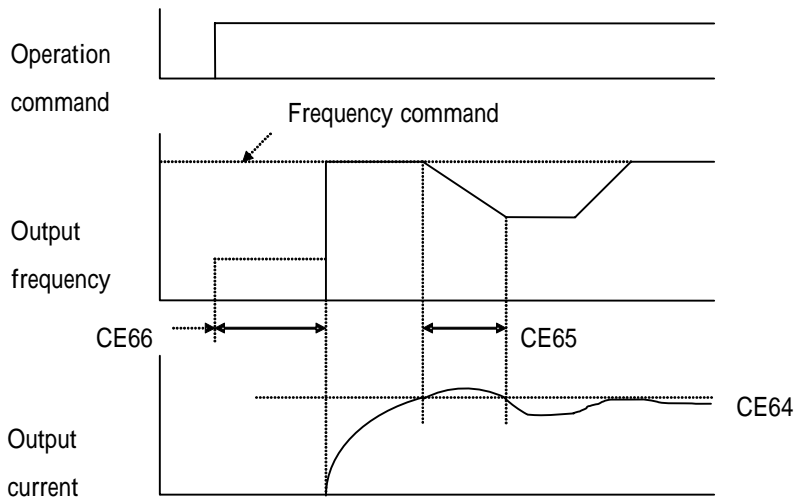
Cd28=1

MCK feedback speed search: search motor rotation speed by MCK feedback signal, then start operation by the speed.



Cd28=2

Current detect + MCK feedback speed search : Start searching motor speed by frequency command or maximum output frequency, when output current is over 120% rated current in searching and start by decreasing output frequency, after current is lower than 120% rated current, then proceed regular operation.



Cd28=3

MCK disconnection start + inertial start: PCB control circuit is unable to operate when disconnection or power voltage is too low. This function is able to automatic search speed and restore setting frequency to operate normal when power reconnection.

§Cd29 Time (Setting range 1-60000)

This function must accommodate Cd47=0 setting.

When motor starts operation, the time counter is active.

§Cd30 Stop by panel key (Setting range 0-1)

Cd30=0 No function

Cd30=1 With function

Stop function: This function enables the inverter to be stopped by panel key while the inverter is operated by external sequence.

§Cd31 Initial factory setting (Setting range 0-1)

The function cannot be modified during operation.

Set data to original factory setting.

Cd31=0 No change

Cd31=1 Initial factory setting, refer to function code table.

Cd31=2 Reset PLC (reset CE05~CE36=0)

Note: After this function is active, content value returns to "0", readable value is always "0".

Adjust and Function Specification

§Cd36 Failure record clear (Setting range 0-1)

Clear the failure record content of code d1-00, 01, 02, and 03.

Cd36=0 No change

Cd36=1 All of the contents of data will be “nOnE”, display of “LoAd” after setting

Note: After this function is active, content value automatically returns to “0”, thus readable value is always “0”.

§Cd37 Frequency gain setting (Setting range 20-200)

Select ratio of frequency gain

Gain setting for external input signals are available using this function.

Output Frequency = Set Value x Frequency Gain x MAX. frequency

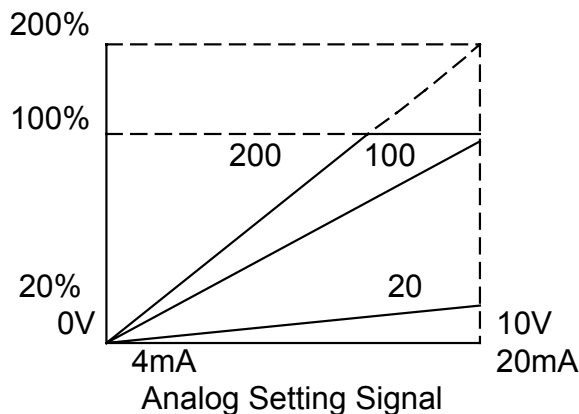
Ex. Under the mode of external voltage (0-10V) frequency setting,

frequency gain = 100%, set voltage to 2V, MAX. frequency (FH) is 120Hz:

Output Frequency = $(2V/10V) \times 120\text{Hz} \times 100\% = 24\text{Hz}$

If change frequency gain to 150%, then

Output Frequency = $(2V/10V) \times 120\text{Hz} \times 150\% = 36\text{Hz}$



Note: If the maximum frequency (FH) exceeds more than 120Hz, gain setting of larger than 100% is ignored and fixed at 100% and input data of Code 37 will not be changed.

§Cd38 Analog output calibration (Setting range 90-110)

Set the ratio of frequency graduation calibration

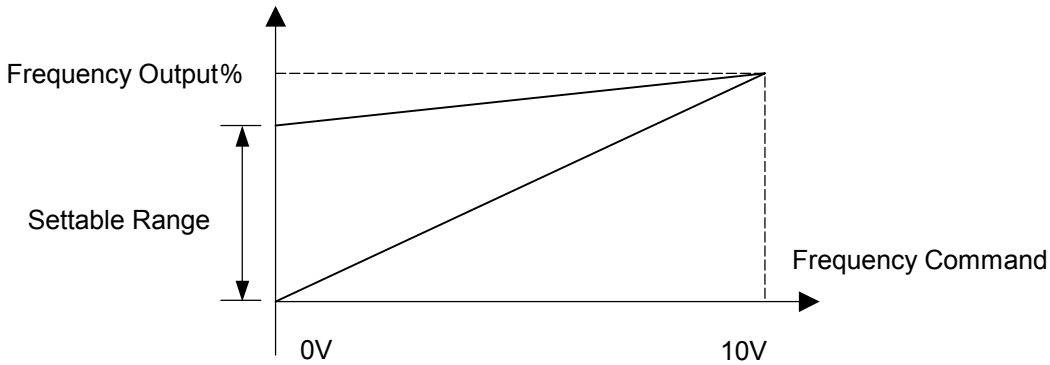
Cd38=99 99% of initial factory

Cd38=101 101% of initial factory

Set Cd54 to select analog output

§Cd 39 Frequency command bias (Setting range 0-250)

External analog frequency command bias setting



§Cd40, 41, 42, 43 Multi-speed setting (Setting range 0-400)

This function has 8 kinds of speed operation

Use external terminal FR (or RR) accommodate 3, 4, 5 to select different speeds. Refer to the following table:

- Cd40= 5th speed setting
- Cd41= 6th speed setting
- Cd42= 7th speed setting
- Cd43= 8th speed setting

Note: Apply to multi-speed setting external control is required for operation control mode (e.g. Cd04=1), and it is also required to set Cd59 for activating common terminal 4.

External terminal Name	Selective speed							
	2	3	4	5	6	7	8	
Terminal 5								
Terminal 3								
Terminal 4								

: stands for external terminal to put in.

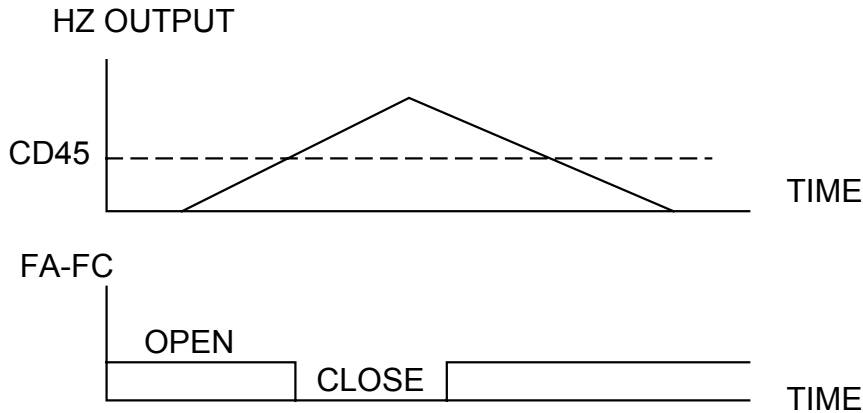
§Cd44 Stop mode (Setting range 0-2)

- Cd44=0 Deceleration stop
- Cd44=1 Free run stop
- Cd44=2 Free run stop, but restart after the deceleration time is reached, deceleration time is set by Cd11.

Adjust and Function Specification

§Cd45 Frequency detect level (Setting range 0-400)

This function is only available when RELAY output terminal Cd47=6 or Cd48=6, and Cd45 is assigned.



§Cd46 Speed multiplier (Setting range 0-500)

The function shows revolution speed multiplied by a scaling factor on the Display.

Note:

1. HZ and A LED de-active.
2. $RPM = \text{Frequency} \times Cd46$

§Cd47 Relay 1 output select (Setting range 0-10)

§Cd48 Relay 2 output select (Setting range 0-10)

The function sets the mode of relay1, relay 2 to activate.

Cd47	Specification	Remark
0	Time counter	Accommodate Cd29
1	Fault	
2	Stop	
3	Acceleration	
4	Speed reached	
5	Deceleration	
6	Frequency reached	Operation frequency > content of Cd45
7	Current reached	Compare to CE73 and CE74 value
8	Over heating prediction action	CE70
9	OL fault action	
10	No action	

§Cd49 Function to lock data (Setting range 0-1)

To lock data, prevent errors by none operator.

Cd49=0 Data change capable

Cd49=1 Data change not capable

§Cd50 Software version (Read only)

This function is to record software version, read only.

§Cd51 Motor rated voltage setting Vr (Setting range 10-450)

This function cannot be modified during operation.

RMS Setting

A. 220V Series: Value of Cd51 = Motor rated voltage / 1

B. 380V Series: Value of Cd51 = Motor rated voltage / 1.73

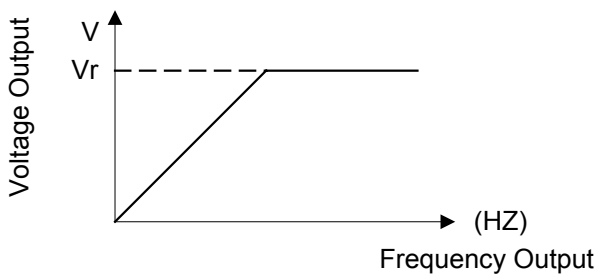
C. 460V Series: Value of Cd51 = Motor rated voltage / 2

Ex.

a. If the motor rated voltage 220Vrms. Power supply voltage 220Vrms, then setting Cd51=220/1=220, then the inverter output Vrate=220Vrms.

b. If the motor rated voltage 380Vrms. Power supply voltage 380Vrms, then setting Cd51=380/1.73=220, then the inverter output Vrate=380Vrms.

c. If the motor rated voltage 460Vrms. Power supply voltage 460Vrms, then setting Cd51=460/2=230, then the inverter output Vrate=460Vrms.



1. $V_{in} > V_{rate}$ when $F_r < F_b$ $V_{out} = F_r / F_b \times V_{rate}$
 when $F_r > F_b$ $V_{out} = V_{rate}$

2. $V_{in} < V_{rate}$ when $V_{out} < V_{in}$ $V_{out} = F_r / F_b \times V_{rate}$
 when $V_{out} > V_{in}$ $V_{out} = V_{in}$

Vin: Power supply voltage

Vout: Inverter output voltage

Vrate: Motor rated voltage

Fr: Inverter revolution frequency

Fb: base frequency

Adjust and Function Specification

§Cd52 Motor no-load current setting (Setting range 5-60)

This function cannot be modified during operation.

The function is to compensate motor vibration during a light-load and fixed speed revolution. This function must accommodate the content of Cd06.

Ex. Motor: 60Hz, 4-pole, 1 horsepower, 220V, no-load current 1.2Arms

Inverter: 1 horsepower, 220V, rated current 4.2Arms, Cd06=100

$$\text{Cd52} = \text{Motor no-load current} / (\text{Inverter rated current} \times \text{Motor rated current ratio Cd06}) \times 100\%$$

$$= 1.2 / (4.2 \times 100\%) \times 100\%$$

$$= 28.5\%$$

§Cd53 Motor slip differential compensation (Setting range 0-10)

This function is to compensate speed variation produced by load variation.

This function must accommodate the content of Cd52.

Setting value 0-100 in relative slip differential 0.0-10.0%

Ex. 60HZ, 4-pole 1700 rpm

Synchronous speed = 1800 rpm

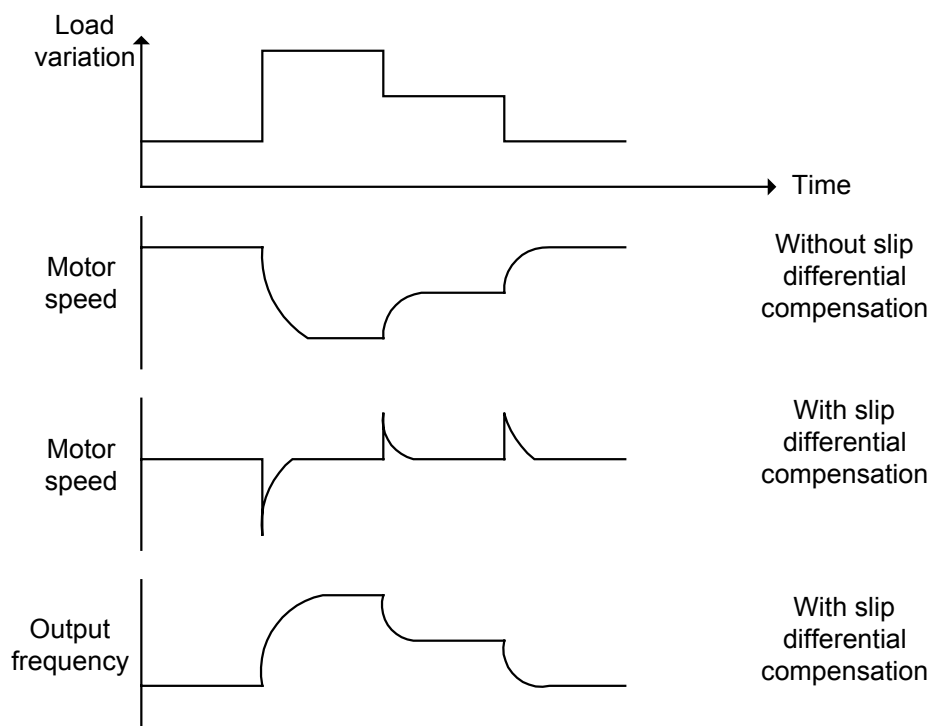
Full-load speed = 1700 rpm

Slip differential speed = 1800-1700=100 rpm

Slip differential % = Slip differential speed / Synchronous speed $\times 100\%$

$$= 100 / 1800 \times 100\% = 5.5\%, \text{ Setting Cd52}=55$$

Slip differential compensation



§Cd54 External analog output selection (Setting range 0-1)

Indicate analog output Vout terminal (0 10V) . Physical definition of output single.

Cd54=0 Indicate output frequency.

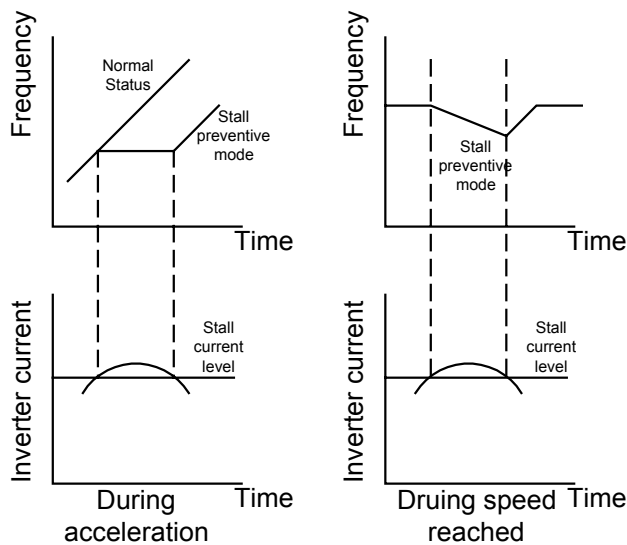
Cd54=1 Indicate output current

§Cd56 Over current stall preventive mode (Setting range 30-200%)

This function is to prevent when motor current exceeds stall current from stall.

There are 2 kinds of acceleration time slopes when motor acceleration current exceeding stall current occurs:

Instantaneous load increase during steady operation and current exceeding over current stall, revolution frequency will drop till current dropped to within stall current level.



§Cd57 Maximum frequency setting FH (Setting range 10-240)

This function cannot be modified during operation.

When Cd05=11, the maximum frequency V/F slope FH

Setting range 10Hz-240Hz

Please refer to function code table.

§Cd58 Base frequency setting Fb (Setting range 10-240)

This function cannot be modified during operation.

When Cd05=11, the base frequency V/F slope Fb

Setting range 10Hz-240Hz (Fb FH)

Please refer to function code table.

Adjust and Function Specification

§Cd59 External terminal 4/6,3/5 function selection (Setting range 0-7)

This function is to select setting common terminal 3,4,5 and 6.

CD59	Common input terminal setting			
	S4	S6	S3	S5
0	JOG	MBS	3DF	2DF
1	JOG/ Yards counter	RST	3DF/ Down speed %	2DF/ UP speed %
2	5DF	MBS	3DF	2DF
3	5DF	RST	3DF	2DF
4	JOG	MBS	DOWN	UP
5	JOG	RST	DOWN	UP
6	5DF	MBS	DOWN	UP
7	5DF	RST	DOWN	UP

Terminal specification:

JOG: Jogging operation, accommodating with Cd15.

5DF: Multi-speed, accommodating with Cd40, 41, 42, 43 speed setting.

MBS: Free run stop, operates both panel key and external signal.

RST: Reset, operates both panel key and external signal

2DF: Second term operation, accommodating with Cd12 speed setting.

3DF: Third term operation, accommodating with Cd13 speed setting.

UP: Using external terminal control on frequency increasing. Max. frequency is setting of Cd00

DOWN: Using external terminal control on frequency decreasing. Min. frequency is setting of Cd16

Note: when use multi-steps function, and Cd59=1, functions of external terminal 3,4,5 are listed as below :

Terminal 3: "Down Speed %", means the speed will be decreased, according to function CE37~CE45.

Terminal 4: Yards counter

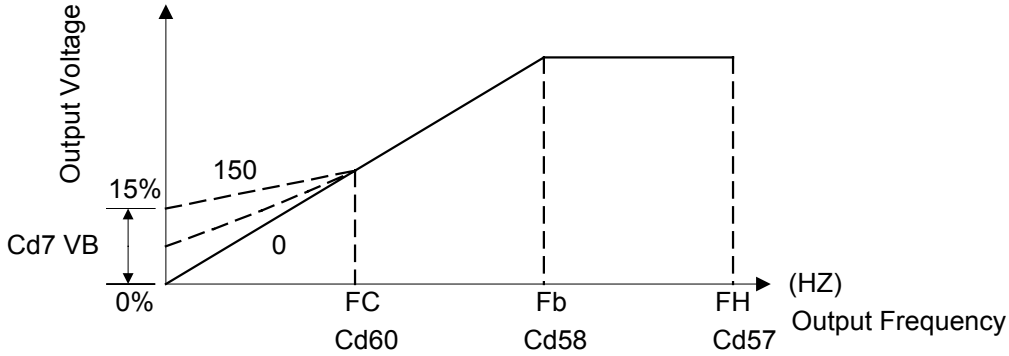
Terminal 5: "Up Speed %", means the speed will be decreased, according to function CE37~CE45.

§Cd60 V / F frequency FC (Setting range 0.5-240)

This function cannot be modified during operation.

To set V/F slope frequency FC when Cd05=11.

Setting range 10Hz-240Hz (FC Fb)



§Cd61 PWM frequency (Setting range 0-4)

This function cannot be modified during operation.

This function is to set PWM frequency.

The higher pitch of PWM & the lower noise of motor, however motor might be shave.

The lower pitch of PMM & the higher noise of motor, however motor should be more stable.

Cd61	PWM Frequency
0	Setting by Cd62 (1.5 – 4.0 Hz)
1	4 KHZ
2	6 KHZ
3	8 KHZ
4	10 KHZ

§Cd62 PWM Frequency2 (Setting range 15-40)

This function cannot be adjusted during operation.

Ex: Cd62 = 15, PWN Frequency = 1.5KHZ

Ex: Cd62 = 30, PWN Frequency = 3.0KHZ

§Cd63@ Switch point for 3rd phase PWM and 2nd phase PWM (Setting range 5-17)

This function is adjustable during revolution

Ex. Cd63 = 5 when output voltage of inverter exceed rated voltage 5%+3%=8%, inverter output shift from 3rd phase PWM to 2nd phase PWM. When output voltage lower than 5% of rated voltage, inverter output shift from 2nd phase PWM to 3rd phase PWM.

Ex. Cd63 = 17 when inverter output voltage exceed rated voltage 17%+3% =20%, inverter output shift from 3rd phase PWM to 2nd phase PWM. When output voltage lower than 17% of rated voltage, inverter output shift from 2nd phase PWM to 3rd phase PWM.

Adjust and Function Specification

§Cd64 Dynamic braking mode (Setting range 0-1)

This function cannot be adjusted during operation.

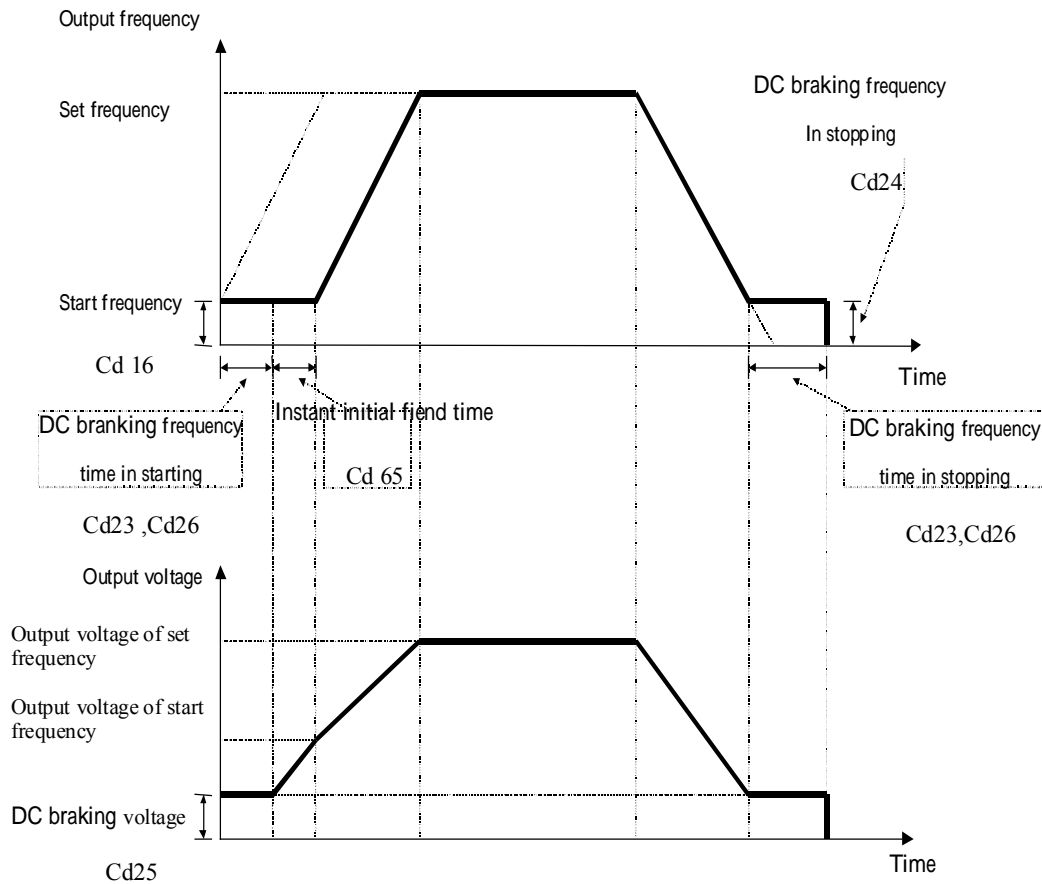
Cd64 = 0 Dynamic braking can be active during acceleration, deceleration and constant speed.

Cd64 = 1 Dynamic braking can be active during acceleration and deceleration, but not active during constant speed operation.

§Cd65@ Instant initial field time (Setting range 0-20)

This function is to adjust instant initial field current of motor.

Shorter of the time, higher of the field current .



§Cd66 Analog input filter time (Setting range 4-64)

This function is adjustable during operation.

Set filter time by Cd66. Set filter time longer. The ability of reject noise is stronger. But reaction of input will be corresponsive slower. Please set suitable time by request.

§Cd67 DC Bus fine tune (Setting range ± 15)

This function is adjustable during operation

This function is to adjust the calibration of voltage positioning on DC BUS between detected and actual position. The display value of Cd02=3 will be lower when Cd67 set at bigger figure. Cd02=3 display will be higher when Cd67 setting at smaller figure.

§Cd68 Dead Time compensation adjustment (Setting range 0-10)

This function cannot be adjusted during operation.

This function is to compensate characteristic differential of IC. Therefore, it should be adjusted in accordance with individual power IC. Motor would be vibrating if this function did not adjust properly. This function has been properly adjusted before ex-factory. Recommend customer not to adjust. If adjustment required, start from “5”, either increase or decrease to a figure that motor operation at the most stable operation.

§Cd70 Dynamic Braking active level (Setting range 120~140)

This function cannot be modified during revolution

This function is to adjust active point of dynamic braking.

Note:

220V series: protection point voltage (VDC)= Cd70 x200V x% x 2

400V series: protection point voltage (VDC)= Cd70 x400V x% x 2

§Cd71 Over Voltage prevention function active point (Setting range 130~150)

This function cannot be modified during revolution

This is to adjust the over voltage protection active point when over voltage occurred.

Note :

220Vseries : active voltage (VDC)= setting value x200V x% x 2

400Vseries : active voltage (VDC)= setting value x400V x% x 2

Adjust and Function Specification

§Cd77 KW-Hour and MW-Hour reset memory (setting range 0-1)

When set Cd77=1, KW-Hour and MW-Hour will be recorded automatically when the power off. When set up successfully, "CLr" will showed, and the record will be cleared to zero.

§Cd79 Auto saving function setting (setting range 0-1)

This function can't be modified during operation.

Cd79=0 Disable auto saving

Cd79=1 Enable auto saving. When power off KW-Hour, MW-Hour, Hanks counter, Current time of PLC and current step PLC will be recorded automatically.

§Cd80 Modbus Protocol and communication mode setting (setting range 0-3)

This function can't be modified during operation.

Selection of operation method on RS485 communication port. Supporting Modbus Protocol.

Cd80=0 RS485 shut down communication interface.

Cd80=1 Active RTU Mode. Parameter change is not allowed.

Cd80=2 Active RTU Mode. Allow changes on general parameter.

Cd80=3 Active RTU Mode. Allow changes on operation instruction and general parameter.

§Cd81 RS485 communication address setting (setting range 1-240)

This function can not be modified during operation.

Corresponding communication address should be set in advance when active RS485 communication function. Inverter is at slave side.

Note: Communication function refers to manuals of interface.

§Cd82 Series communication baud rate setting (setting range 0-2)

This function can't be modified during operation.

Setting of Baud rate during communication

Cd82=0 2400 bps

Cd82=1 4800 bps

Cd82=2 9600 bps

Note: Re-start inverter after setting Baud rate.

§Cd83 Series communication response time setting (setting range 0-15)

This function cannot be modified during revolution.

Setting waiting time for response when inverter receive correction data.

MODBUS RESPONSE TIME=(0 ~ 8ms) + (8ms * CD83)

§Cd84 Series communication broadcasting function setting (setting range 0-1)

This function can't be modified during operation.

When setting communication, wither active group broadcasting (MODBUS Function 241~255) or global broadcasting (MODBUS Function 0) function.

Cd84=0 Active group broadcasting, de-active global broadcasting.

Cd84=1 De-active both group and global broadcasting.

§Cd85 LCD Display Setting (Setting range 0-2)

Initial Factory Setting: 0

Cd85=0 Display 2 parameter in LCD

Cd85=1 Display 4 parameter in LCD

Cd85=2 Display 8 parameter in LCD

§Cd87 Display Group of LCD monitor (Setting range 0-3)

Initial Factory Setting: 0

Example: Cd85=2, Display 8 parameter in LCD, Groups as below.

Group 1	
Frequency	Speed
Amp	KW-H
Power	Temp.
AvqSp	AC V

Group 2	
Frequency	Temp
Amp	COS θ
Vdc	Poewr
AC V	KW-H

Group 3	
Speed	Step
Amp	Time
Vdc	Yards
AC V	AvqSp

Group 4	
Frequency	Ext
Amp	MCK
Vdc	Temp.
AC V	KW-H

§d1-29,30,31,32 Failure record

Record cause of failure, in order to solve failure.

Note: 1. Cannot record failure Err, Ero, Erc.

2. Only memorize 4 records.

3. Cannot record inverter stopped by low voltage.

4. Read only d1-29,30,31,32 or delete all (Cd36), cannot put in failure record by operator.

§CE05 - CE20 Multi-step function control frequency setting (setting range 0-400HZ)

Maximum 16 steps.

- CE05 1st step speed setting
- CE06 2nd step speed setting
- CE07 3rd step speed setting
- CE08 4th step speed setting
- CE09 5th step speed setting
- CE10 6th step speed setting
- CE11 7th step speed setting
- CE12 8th step speed setting
- CE13 9th step speed setting
- CE14 10th step speed setting
- CE15 11th step speed setting
- CE16 12th step speed setting
- CE17 13th step speed setting
- CE18 14th step speed setting
- CE19 15th step speed setting
- CE20 16th step speed setting

§CE21 - CE36 Multi-step process control time setting (setting range 0-255Min)

Maximum 16 steps. End of entire procedure if time setting = 0.

- CE21 1st step time setting
- CE22 2nd step time setting
- CE23 3rd step time setting
- CE24 4th step time setting
- CE25 5th step time setting
- CE26 6th step time setting
- CE27 7th step time setting
- CE28 8th step time setting
- CE29 9th step time setting
- CE30 10th step time setting
- CE31 11th step time setting
- CE32 12th step time setting
- CE33 13th step time setting
- CE34 14th step time setting
- CE35 15th step time setting
- CE36 16th step time setting

§CE37 1st frequency increase setting (setting range 0.0-10.0%)

(1st Bob up speed %)

Set the 1st frequency increase percentage. The setting is related with current working speed of inverter.

When Inverter working under multi-step function mode(Cd01=7), and CE47=2, or 3, Cd59=1, short terminal 5(UP) and COM, then the speed will be

Operation frequency = current steps' frequency + (current steps' frequency xCE37)

§CE38 2nd frequency increase setting (setting range 0.0-10.0%)

(2nd Bob up speed %)

Set the 2nd frequency increase percentage.

§CE39 3rd frequency increase setting (setting range 0.0-10.0%)

(3rd Bob up speed %)

Set the 3rd frequency increase percentage.

§CE40 Setting Times of 1st frequency increase (setting range 0-200min)

(1st Bob up speed % time)

Set the time of 1st frequency increase percentage.

When multi-step operation time shorter than CE40, CE37 will be the current frequency increase order. If CE40=0 it will use CE37 as frequency increase order, no matter what is the perform time in multi-step function.

§CE41 Setting Times of 2nd frequency increase (setting range 0-200min)

(2nd Bob up speed % time)

Set the time of 2nd frequency increase percentage.

When multi-step function operation time longer than CE40 and shorter than CE41, the frequency will increased as CE38. If CE41=0 it will use CE38 as frequency increase order, no matter what is the perform time in multi-step function.

When multi-step operation time is longer or equal to CE41, it will use CE39 as current frequency increase order.

§CE42 1st frequency decrease setting (Setting range 0.0-10.0%)

(1st Bob down speed %)

Set the 1st frequency decrease percentage. The setting is related with current working speed of inverter. When inverter working under multi-steps function mode(Cd01=7), and CE47=2, or 3, Cd59=1, short external terminal 3(DOWN) and COM, then the speed will be Operation frequency = current steps' frequency – (current steps' frequency xCE42)

§CE43 2nd frequency decrease setting (Setting range 0.0-10.0%)

(2nd Bob down speed %)

Set the second frequency decrease percentage.

§CE44 3rd frequency decrease setting (Setting range 0.0-10.0%)

(3rd Bob down speed %)

Set the third step frequency decrease percentage.

§CE45 Setting Times of 1st frequency decrease (setting range 0-200min)

(1st Bob down speed % time)

Set the time of 1st frequency decrease percentage.

When multi-steps operation time shorter than CE45, CE42 will be the current frequency decrease order.

If CE45=0 it will use CE42 as frequency decrease order, no matter what is the time of the perform time in multi-step function.

§CE46 Setting Times of 2nd frequency decrease (setting range 0-200min)

(2nd Bob down speed % time)

Set the time of 2nd frequency decrease percentage.

When multi-steps operation time longer than CE45 and shorter than CE46, the frequency will decrease as CE43.

If CE46=0 it will use CE43 as frequency decrease order, no matter what is the perform time in multi-step function. When multi-steps operation time longer or equal to CE46, it will use CE44 as current frequency decrease order.

§CE47 Multi steps function modes selection (setting range 0-3)

The function cannot be modified during operation.

Select operation modes on speed variation when process control switch from previous step to next step.

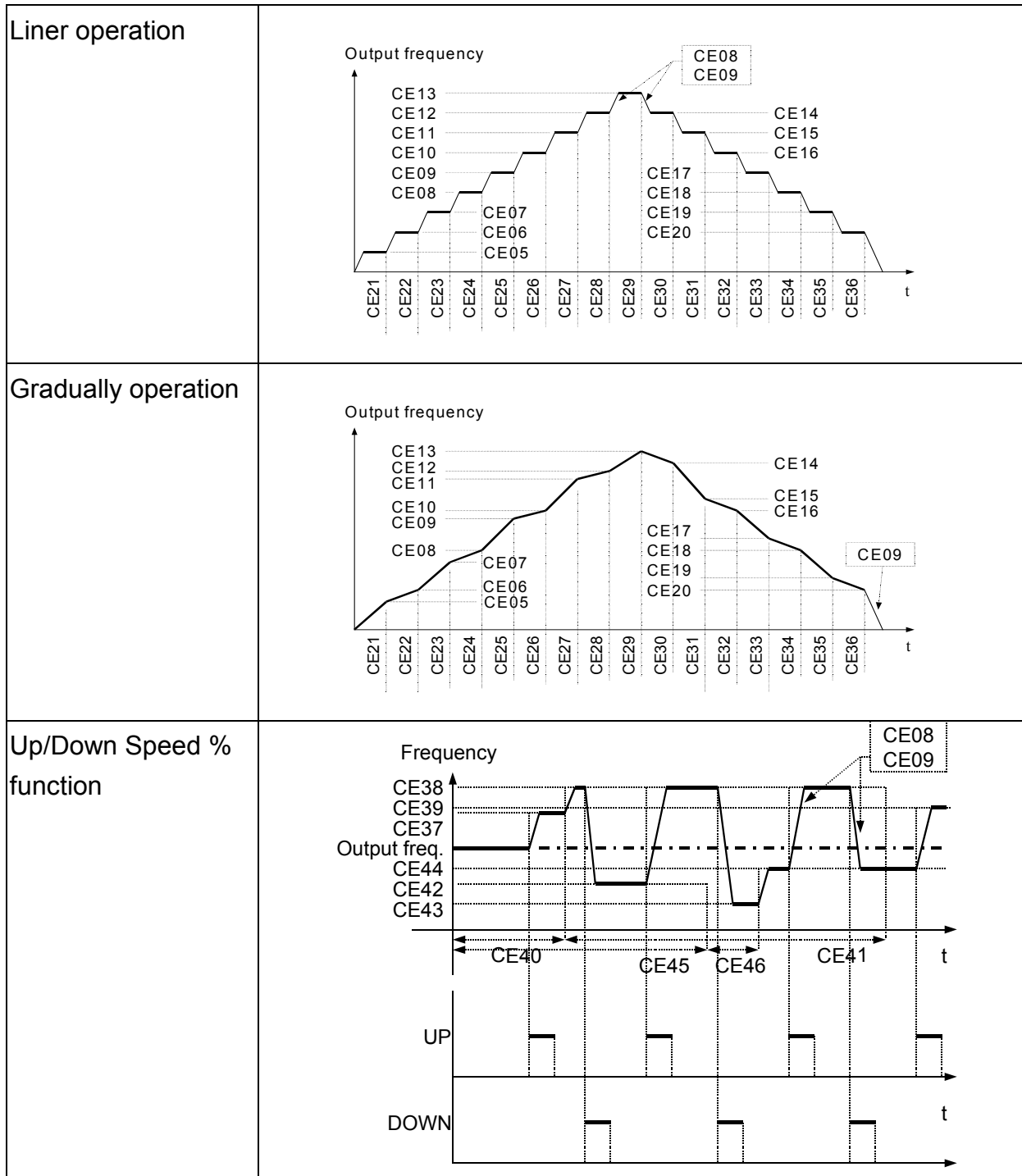
CE47=0 Liner operation

CE47=1 Gradually operation. (Perform time can set to zero, when perform time set to 0, perform time will according to CD08, CD09 increase or decrease. If the step frequency set to 0, the step will be ended.)

CE47=2 Liner operation use Up/Down Speed % function.

CE47=3 Gradually operation use Up/Down Speed % function. (Perform time can set to zero, when perform time set to 0, acceleration/deceleration time will according to CD08, CD09. If the steps' frequency set to 0, the step will be ended.)

Adjust and Function Specification



§CE48 Multi steps function operation reset (setting range 0-1)

The function cannot be modified during operation.

Memorized of current operation step and time (in sec) while shut down or power failure.

Step and time reset to 0 when set CE48=1.

Note: External terminal 6 set to RST function, when RST connect with COM, it will reset the records and steps time to 0.

§CE49 Multi steps process control continuous operation (setting range 0-2)

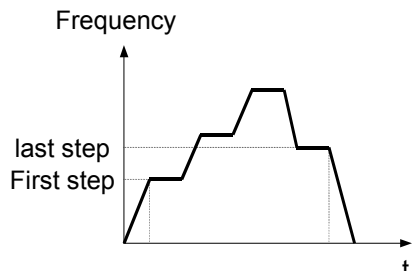
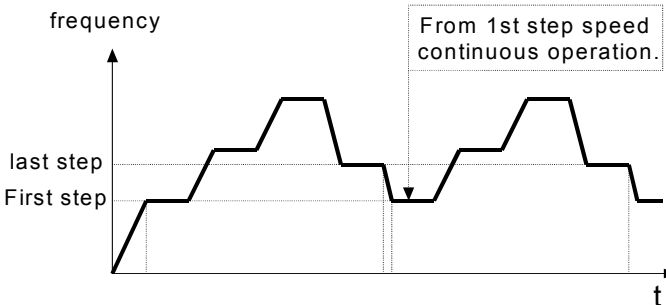
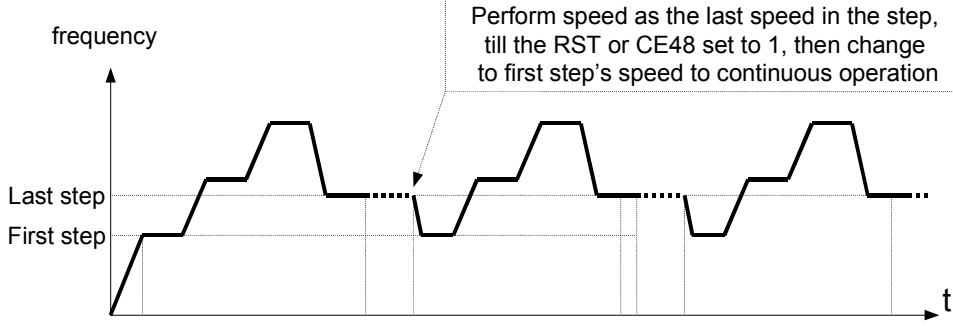
The function cannot be modified during operation.

Selection of shut down or start from 1st step while entire operation procedure finished.

CE49=0 Not continuous operation.

CE49=1 Continuous operation. From 1st steps' speed continuous operation.

CE49=2 Continuous operation, perform speed as the last speed in the step, till the RST or CE48 set to 1, then change to first step's speed.

<p>Not continuous operation</p>	
<p>Continuous operation</p>	
<p>Continuous operation, perform speed as the last speed in the step, till the RST or CE48 set to 1</p>	

§CE50@ Multi-step function time error adjust (setting range 0-256Hz)

§CE52 Choice of multi-speed record file (setting range 1-6)

The function cannot be modified during operation.

The setting cannot be changed while the machine is working.

According to the needs of the user, choose different file for the current step, the data CE05~CE46 are stored in the files.

Adjust and Function Specification

§CE53 Multi-steps all files set to default (setting range 0-1)

The function cannot be modified during operation.

The setting can not be changed while the machine is working.

CE53=0 Data remain unchanged.

CE53=1 Reset data in files 1-6 to default.

§CE54 Multi-steps memory duplicate function (setting range 1-6)

The function cannot be modified during operation.

The setting cannot be changed while the machine is working.

Duplicate current using file (CE05~CE46) to CE54 .

§CE55 Yards counter clear (setting range 0-1)

Set CE55=1 to clear Yards counter.

§CE56 Stall prevention selection during acceleration (setting range 0-1)

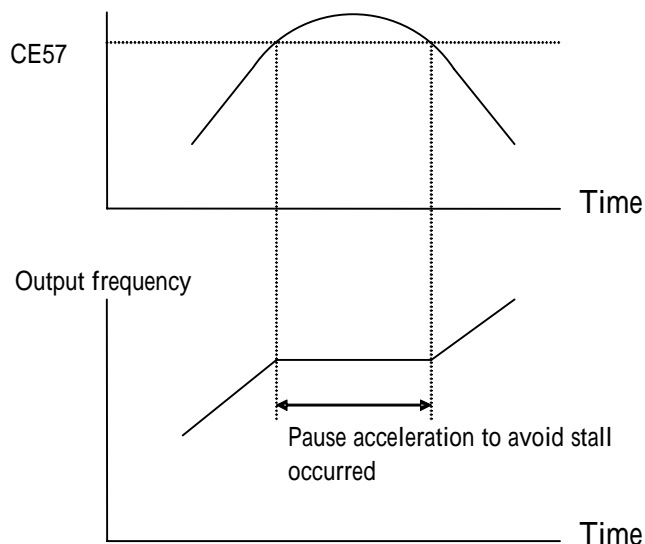
§CE57 Stall prevention level during acceleration (setting range 30-200)

When a heavy load is placed on the motor or acceleration time is too short during acceleration. Due to current output too much to lead inverter to over current, it can prevent from motor stall. The inverter will stop accelerating when output current exceeds CE57 during acceleration.

CE56= 0, invalid

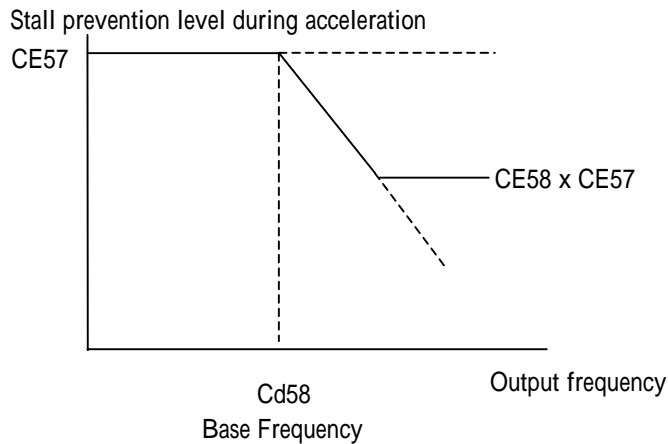
= 1, valid

CE57: Setting method, set inverter rated current to 100%



§CE58 Stall prevention limit during acceleration (setting range 30-100)

If using the motor in the constant output range, and automatically lowered to prevent stalling, Disable to prevent the stall prevention level in the constant output range from being reduced more than necessary.



§CE59@ Stall prevention limit during deceleration (setting range 0-1)

§CE61@ Stall prevention selection during constant speed operation (setting range 0-1)

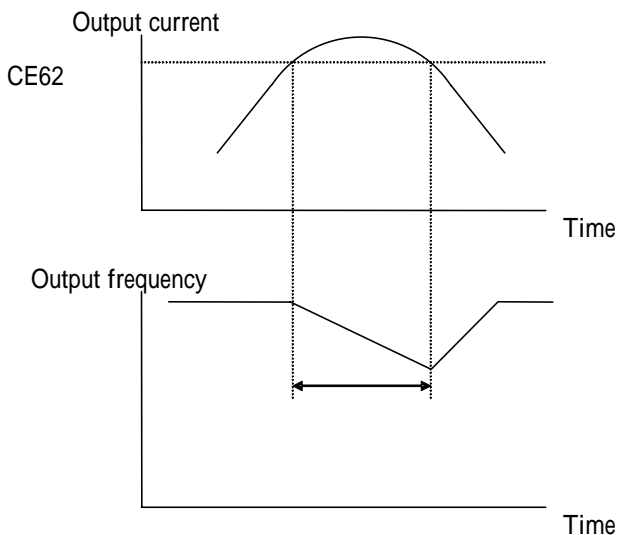
§CE62@ Stall prevention level during constant speed operation (setting range 3-200)

A heavy load is placed on the motor when constant operation and makes inverter output current exceed CE62 setting value. The inverter will automatically reduce output frequency to prevent the motor from stall (OC/OL). When a load disappeared or lightened and makes inverter output current be smaller than CE62 setting value. The inverter will automatically accelerate to work frequency.

CE61= 0, invalid

= 1, valid, decelerated by Cd11 deceleration time.

CE62 setting method: Set 100% as inverter rated current.



Description of alarm display indications

§CE63@ Low voltage prevention active point (setting range 155-500)

The function is to set input voltage.

CE63=220 : The working voltage is $220 \times 0.85 = 187$ Vac

CE63=380 : The working voltage is $380 \times 0.85 = 323$ Vac (can't lower than 310Vac)

CE63=415 : The working voltage is $415 \times 0.85 = 352$ Vac (can't lower than 340Vac)

CE63=440 : The working voltage is $440 \times 0.85 = 374$ Vac (can't lower than 360Vac)

CE63=460 : The working voltage is $460 \times 0.85 = 391$ Vac (can't lower than 376Vac)

§CE67@ Momentary power loss direction (setting range 0-2)

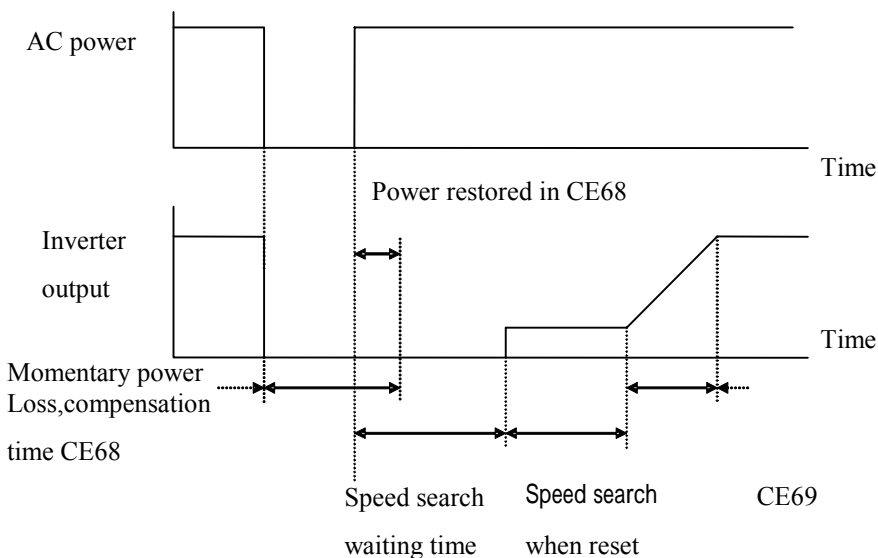
§CE68@ Momentary power loss compensation time (setting range 0-2)

§CE69@ Voltage recovery time (setting range 0-20)

If a temporary power loss occurs, user can restart the inverter automatically after power restored to continue motor operation. To restart the inverter after power restored, set CE67= 1 or 2.

If CE67= 1, when power is restored within the time set in CE68, the inverter will restart. If the time is over, UV (under voltage) will be detected.

If CE67= 2, when power is restored while the control power supply is kept CPU to work, the inverter will restart UV (under voltage) will be cleared automatically. Speed search setting is collocated when use momentary stop and restart.



§CE70@ Inverter overheating forecast detection level (setting range 50-100)

§CE71@ Active when inverter overheating forecast detection(setting range 0-3)

§CE72@ Temperature protection level (setting range 50-130)

Set action when inverter detects action point and overheating.

Set CE72 to Inverter overheating detection level. OH1 is displayed and inverter will stop free run when it is detected.

CE70 set Inverter overheating forecast level, set CE72 to 100%. Select operation by CE71 when overheating forecast occurred.

CE71	Description
0	Deceleration stop (Inverter is stopped by deceleration time)
1	Free run stop
2	Emergency stop (Inverter is stopped by Cd11)
3	Continuous operation, OH b displays overheating forecast

When motor operation exceeds motor rated current, it is overload operation, and it might damage motor if under overload operation for long time.

§CE73@ Current arrearage range (setting range 2-20)

§CE74@ Current detect level (setting range 30-150)

Set the action range of current detect.

Current arrearage range: RELAY will jump when Cd47, 48, 49=7, current is lower than rated current (CE73 - CE74) value

Current detect level: RELAY will start when Cd47, 48, 49=7, current is over rated current × CE74 value.

Description of alarm display indications

7. Description of alarm display indications

Error indication	Description of fault operation	Item for inspection	Processing
Err	Operation error	Was the unit operated as indicated in the manual	Use the correct procedure
ErO	Operation error of internal ROM, RAM	Switch off the power and then apply again	Replace the unit
ErC	Error of internal CPU	Is there a large amount of external noise	Check the contact absorber. Install a noise filter
OCPA	Over current (180% rated current)	Was there rapid acceleration	Lengthen the acceleration time
OCPd	Over current (180% rated current)	Was there rapid deceleration	Lengthen the deceleration time
OCPn	Over current (180% rated current)	Was there any variation in the load	Lengthen the time for the load variations
OC	Over current (200% rated current)	Was there rapid acceleration / deceleration and variation in the load	Lengthen the acceleration and deceleration time and reduce the load
OCS	Output short circuit or ground detected	Is there a short circuit for the output or grounding for the motor	Perform a megger check for the motor
OU	DC link over voltage	Was there fast deceleration, or fast voltage	Lengthen the deceleration time. Investigate the use of the optional DBR
LU	Insufficient voltage detected due to power failure or instantaneous power loss.	Is there a low voltage at power, or internal inverter wiring error	Improve the voltage condition and confirm inverter model
LU A	Insufficient voltage detected due to power failure or instantaneous power loss. And the auto save function is working	Is there a low voltage at power, or internal inverter wiring error	Improve the voltage condition and confirm inverter model

Description of alarm display indications

Error indication	Description of fault operation	Item for inspection	Processing
OH	Overheating of the cooling fan detected	<ol style="list-style-type: none"> 1. Cooling fan stops 2. Ambient temperature too hot 3. Motor being overload 	<ol style="list-style-type: none"> 1. Exchange the cooling fan 2. Lower the ambient temperature 3. Check the load conditions
OL	Overload detected for more than one minute	Is the motor being overloaded	Increase the capacity of the inverter and motor
OL A	Overload warning, the motor is nearly 1min, 150% overload.	Is the motor being overloaded	Increase the capacity of the inverter and motor
bUOH	DBR overheat detected	Is the braking ratio appropriate	Reduce GD^2 of load or lengthen deceleration time
ES	Emergency switch active	Check if DI6 and COM are open.	Short DI6 and COM
Fb	Fuse blown	Is the fuse blown	Change a fuse
PLU	Power voltage too low	Is power voltage too low	Improve power supply condition

Troubleshooting

8. Troubleshooting

Description of trouble	Possible cause	Solution
The motor does not run at all	1. Wiring error	Refer to the wiring diagram 1. Check the power input wiring 2. Is there a voltage for U.V.W output
	2. Wrong settings at operator panel	The function code No.04 is as follows 0: Panel key operation 1: External signals
	3. Inverter displays fault indication	Refer to "Protect Function"
	4. Motor cannot start due to overload	Exchange a higher capacity one
	5. Motor breaks down	Repair motor
	6. Inverter breaks down	Please contact us
"OCPA" is indicated as soon as the motor is started. (Overcurrent protects operation during acceleration.)	1. Motor wiring error	Refer to the wiring diagram
	2. Overload	Reduce the load or increase inverter capacity
	3. Is V/F slope appropriate	Check Code 05 V/F slope is appropriate with motor specification
	4. Is start torque appropriate	Adjust Code 07 torque boost to overcome steady friction but not over current trip.
	5. Is the acceleration time too short when compared to load GD^2	Lengthen acceleration time by apply Code 08 and Code 10 or increase inverter capacity
	6. The inverter is starting during motor free-run	Refers to Code 28, change the value from 0 to 1
"OCPd" is indicated as the motor is decelerating. (Over current protects operation during deceleration).	1. Deceleration time too short, unable to be loaded	Apply Code 09 and Code 11 to lengthen deceleration time or increase inverter capacity

Description of trouble	Possible cause	Solution
“OC” or “OCS” is indicated during operation. (Over current)	1. Short circuit on U.V.W or grounding for motor	Exclude short circuit or grounding
	2. Instantaneously mechanical load on motor	Reduce load or increase inverter capacity
	3. Motor breaks down	Repair motor
	4. Inverter breaks down	Please contact us
“OU” is displayed during inverter operation	1. Is power voltage with the specification	Improve power voltage condition
	2. Braking resistor not applied	Apply braking resistor, increase braking ratio
	3. Deceleration time too short, unable to be loaded	Apply Code 09 and Code 11 to lengthen deceleration time
“PLU” is displayed during inverter operation	1. Is power voltage with the specification	Improve power voltage condition
	2. Instantaneous power voltage failure	Check the capacity of the power facilities
	3. Power dropped and the protector function has operated	Check the capacity of the power facilities
“OL” is displayed during inverter operation	1. Overload	Reduce load or increase inverter capacity
	2. Is inverter over current limiter appropriate	Apply Code 06 to re-set motor rated current
“OH” is displayed during inverter operation	1. Check if the cooling fan is still working	Change cooling fan and clean dirt
	2. Is ambient temperature too hot	Improve ambient temperature condition
No any indication, the output frequency displayed “0”	1. Power failure	Check the capacity of the power facilities
	2. Is there loosen part on external control terminal	Check external control terminal

9. Maintenance and Inspection

Maintenance and inspection must be taken under power off.

Cautions on maintenance and inspection:

- (1) Capacitor is charged at high voltage for a while after turning off the power.
(Accordingly, start the inspection work at least 5 minutes after turning off the power)
- (2) Do the work with operator.

Inspection items:

- (1) Please check the following items
 - A. Motor runs as expected.
 - B. Avoid installing on circumstances like acid, alkaloid.
 - C. No trouble is recognized in the cooling system and irregular vibration or noise.
 - D. No parts is overheated or burned.
- (2) Periodic inspection

Interval	Inspection item
Every 6 months	<ol style="list-style-type: none">1. Terminal plates and mounting bolts.2. Corrosion and breaks in the terminal clips for the wiring.3. Condition for the connector fixing.
Once a year	<ol style="list-style-type: none">1. Use clean, dry air to remove dust buildup from the guards, the stack and the cooling fan.2. Check for parts burns or damage and make any exchanges necessary.

10. Standard Specification

A. CT2000PLUS/PRO 200Vseries

Motor rating (KW)	2.2	3.7	5.5	7.5	11	15	22	30	37	45	55	75	93
Model CT2000PLUS- CT2000PRO-	2A2	3A7	5A5	7A5	011	015	022	030	037	045	055	075	093
Rated current (A)	11.1	18	23	33	48	61	86	125	150	170	210	278	330
Rated capacity (KVA)	4.4	7.1	9.2	13.1	19.1	24.3	34.3	49	60	68	84	111	131
Power supply	3 200~230V ±10% 50HZ ±5% or 3 200~230V ±10% 60HZ ±5%												
Output voltage	3 200V、220V、230V												
Cooling system	Forced air-cooling												
Outline dimension	Fig1	Fig1	Fig1	Fig2	Fig2	Fig2	Fig2	Fig2	Fig2	Fig2	Fig2	Fig2	Fig2
Weight (Kg)	8	8	9	14	14	20	30	45	60	60	65	70	70

B. CT2000PLUS/PRO 400Vseries

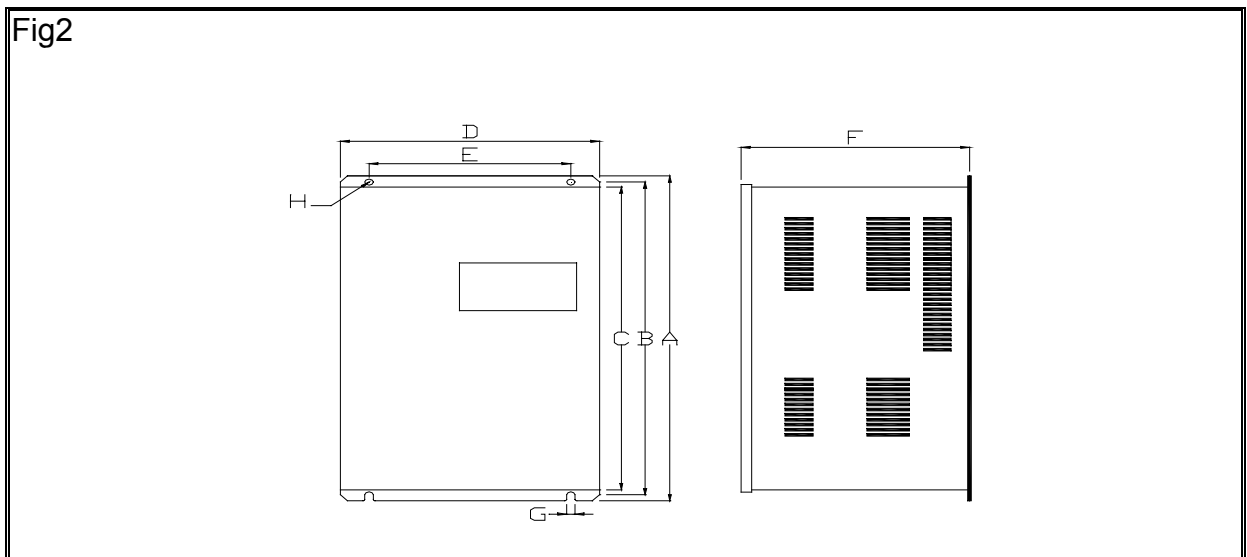
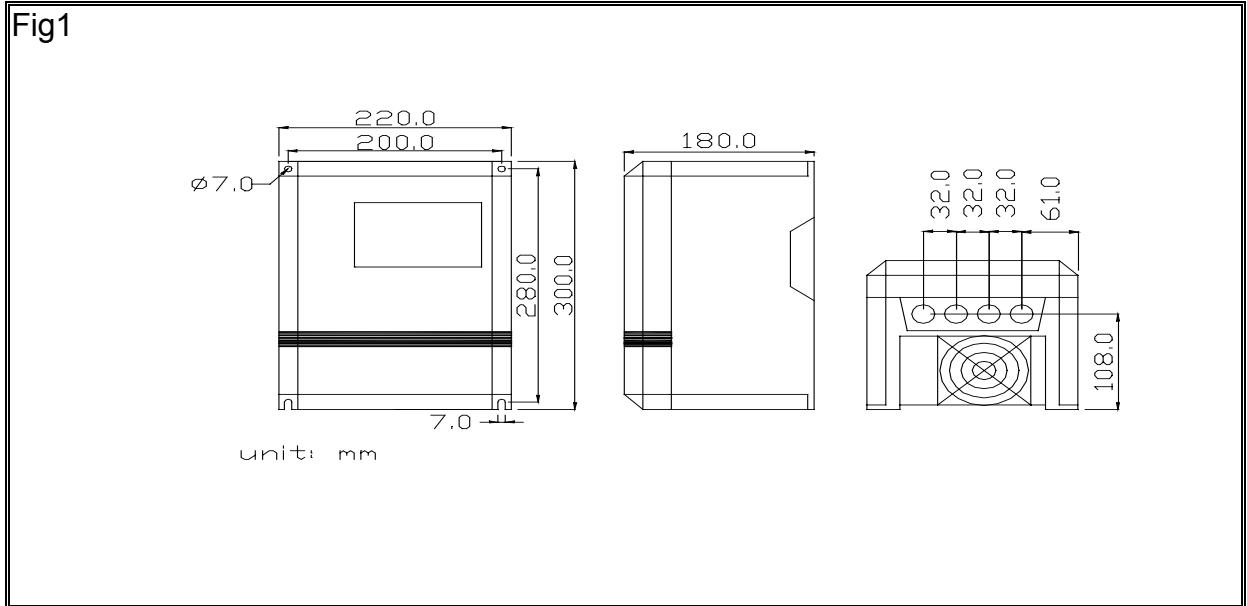
Motor rating (KW)	2.2	3.7	5.5	7.5	11	15	22	30	37	45	55	75	93	112
Model CT2000PLUS- CT2000PRO-	2A2	3A7	5A5	7A5	011	015	022	030	037	045	055	075	093	112
Rated current (A)	6.2	9	13	17.3	24	31	52	65	71	93	110	156	180	225
Rated capacity (KVA)	4.9	7.1	10.4	13.8	19.1	24.7	41.4	51.8	56.6	74	87.6	124	143	180
Power supply	3 380~460V ±10% 50HZ ±5% or 3 380~460V ±10% 60HZ ±5%													
Output voltage	3 380V、400V、440V、460V													
Cooling system	Forced air-cooling													
Outline dimension	Fig1	Fig1	Fig1	Fig2	Fig2	Fig2	Fig2	Fig2	Fig2	Fig2	Fig2	Fig2	Fig2	Fig2
Weight (Kg)	8	9	9	14	14	18	35	38	40	46	50	65	70	70

Standard Specification

C. Standard specification

Control method	Sine P.W.M control	
Frequency accuracy	Digital setting: $\pm 0.1\%$ Analog setting: $\pm 0.5\%$ (35)	
Frequency resolution	Digital setting: 0.5 100Hz 0.01Hz 100Hz 240Hz 0.1Hz Analog setting: (setting value/1000)Hz	
Frequency range	0.5 240HZ (Initial frequency 0.5 30Hz)	
V/F ratio	10 patterns, or any V/F patterns.	
Torque boost	0 15.0% voltage boost, automatic voltage boost	
Acceleration / Deceleration time	0.1 6000 sec (linear, two-step setting)	
Motor Braking	100% DB. Under 3.7KW Including braking resister.	20% DB. Connect extra braking resister to reach 100% DB.
DC Braking	DC Injection Braking (Setting mode, torque, time, active frequency)	
Standard feature	Free run restart, jogging speed, upper/lower frequency limit setting, jump frequency setting, 8-step speed setting, frequency increase/decrease (UP/DOWN) function, BIAS, frequency indicated output (DC0 10V), operation direction setting, forward/reverse prohibit, voltage/current limit, data lock, multi-step function, auto record when power off, 6 memory pattern of multi-step function.	
Frequency setting	Digital setting by keypad, or external analog signal (DC0 10V , DC4 20mA)	
Display	7-segment LED display: Frequency, current, voltage, setting value, function, fault status, Temperature of PIM module, status of multi-step function, average speed of multi-step function, instant power, power factor, Kwh, Mwh.	
Protection	Low voltage, over voltage, instantaneous power failure, over voltage stall, overload, over current stall, instantaneous over current, acceleration over current, deceleration over current, over heat.	
Overload capacity	150% for 1 min, anti-time limit function, adjustable (25 100 %)	
Altitude	Altitude 1,000m or lower, keep from corrosive gasses, liquid and dust	
Ambient Temperature	-10 50 (Non-condensing and not frozen)	
Vibration	Below 0.6G	
Humidity	Relative between 45 % to 90% (No condensing)	

D. Outline dimension : (unit: mm)



220V Series								
KW	A	B	C	D	E	F	G	H
7.5/11	430	414	401	244	190	215	7	7
15/22	492	477	466	283	200	254	7	7
30 45	699	679	668	408	270	314	10	10
55 93	912	892	872	530	350	313	10	10
400V Series								
KW	A	B	C	D	E	F	G	H
7.5/15	430	414	401	244	190	215	7	7
22/30	492	477	466	283	200	254	7	7
37 55	699	679	668	408	270	314	10	10
75 112	912	892	872	530	350	313	10	10

Function Code Table

11. Function Code Table

Code No.	Function	Detail of Data	Initial factory setting	MODBUS Address
Cd00	Set frequency	0-400Hz	10	128
Cd01	Setting procedure of frequency	0: Operation panel Cd00 1: External IN2 (0-10V) 2: External IN1 (4-20mA) 3: External IN2+IN3 (0-10V) 4: External IN2 (0-10V)hysteresis 5: External IN1 (4-20mA)hysteresis 6: External IN2+IN3 (0-10V) hysteresis 7: Multi-steps control	5	129
Cd02	Select monitor display	0: Frequency (HZ) 1: Current (A) 2: Ultimate speed 3: DC Voltage(d) 4: Output AC Voltage(V) 5: External I/O status(E) 6: Temperature of PIM module(b) 7: operation frequency feedback 8: average speed of multi-step function. 9: current step of multi-step function 10: current time of multi-step function (min) 11: Yards counter 12: power factor 13: instant power (Kw) 14: KWh 15: MWh	0	130
Cd03	Torque mode	0: Without auto boost 1: 3Hz above with auto boost 2: 1.5Hz above with auto boost and frequency compensation 3Hz above without frequency	1	131
Cd04	Operation command mode	0: Operation panel 1: External signal	0	132

Function Code Table

Code No.	Function	Detail of Data	Initial factory setting	MODBUS Address
Cd05	Set V/F pattern	1-7 fixed Modes 11: Set by CD57, CD58	3	133
Cd06	Motor current rate	25-100%	100	134
Cd07	Torque boost	0-15.0 (0-15.0%)	2	135
Cd08	1 st acceleration time	0-6000 (S/50HZ)	5	136
Cd09	1 st deceleration time	0-6000 (S/50HZ)	5	137
Cd10	2 nd acceleration time	0-6000 (S/50HZ)	10	138
Cd11	2 nd deceleration time	0-6000 (S/50HZ)	10	139
Cd12	No.2 frequency	0-400HZ	20	140
Cd13	No.3 frequency	0-400HZ	30	141
Cd14	No.4 frequency	0-400HZ	40	142
Cd15	Jogging frequency	0-60HZ	5	143
Cd16	Start frequency	0.5HZ-60HZ	5	144
Cd17	Upper limiter frequency	10-400HZ	60	145
Cd18	Lower limiter frequency	0-100HZ	0	146
Cd19	Jogging acceleration / deceleration time	0-600(S/50HZ)	1	147
Cd20	Jump frequency 1	0-400HZ	0	148
Cd21	Jump frequency 2	0-400HZ	0	149
Cd22	Jump frequency width	0-6HZ	0	150
Cd23	Braking mode	0: de-active 1: Active when stop 2: Active when start 3: Active both stop and start	0	151

Function Code Table

Code No.	Function	Detail of Data	Initial factory setting	MODBUS Address
Cd24	DC braking frequency	0-20HZ	1	152
Cd25	DC braking voltage	0-100	50	153
Cd26	DC braking time	1-60 Sec.	1	154
Cd27	Run direction	0: Reverse 1: Prohibited reverse	0	155
Cd28	Speed search selecting	0: Invalid 1: MCK feedback 2: Detected current +MCK feedback 3: MCK disconnection start + coast start	0~3	156
Cd29	Time	1-60000 (Sec.)	5	157
Cd30	Stop by panel key	0: Impossible 1: Possible	1	158
Cd31	Initial factory setting	0: No change 1: Initial factory setting 2:Reset CE05~CE36=0	0	159
Cd36	Memory clear for fault annunciation	0: No change 1: Memory clear	0	164
Cd37	Frequency gain setting	20-200%	100	165
Cd38	Analog output calibrate	90-110%	100	166
Cd39	Frequency command bias	0-250	125	167
Cd40	No.5 Frequency	0-400HZ	45	168
Cd41	No.6 Frequency	0-400HZ	50	169
Cd42	No.7 Frequency	0-400HZ	55	170
Cd43	No.8 Frequency	0-400HZ	60	171

Function Code Table

Code No.	Function	Detail of Data	Initial factory setting	MODBUS Address
Cd44	Stop mode	0: Decelerate stop 1: Free run stop 2: Free run stop after deceleration time is reached	0	172
Cd45	Frequency detect level	0-400HZ	0.5	173
Cd46	Speed multiplier	0-500	1	174
Cd47	Relay 1 output select	0-10	1	175
Cd48	Relay 2 output select	0-10	1	176
Cd49	Lock data	0: Data change capable 1: Data change not capable	0	177
Cd50	Software version	Read only	x	178
Cd51	Motor rated voltage	Each factory value of each model	10-450	179
Cd52	Motor no-load current	5-60%	30	180
Cd53	Motor slip differential boost	0.0-10.0%	0	181
Cd54	External analog output select	0: Display output frequency 1: Display output current	0	182
Cd55	Field select	0~60%	20	183
Cd56	Current stall preventive	30-200%	180	184
Cd57	Max. frequency setting FH	10-240HZ (FH)	240	185
Cd58	Base frequency setting Fb	10-240HZ (Fb) FH Fb	240	186

Function Code Table

Code No.	Function	Detail of Data					Initial factory setting	MODBUS Address
		Set	DI4	DI6	DI3	DI5		
Cd59	External terminal 4/6,3/5 function selection	0	JOG	MBS	3DF	2DF	1	187
		1	JOG/yards	RST	3DF/Down%	2DF/Up%		
		2	5DF	MBS	3DF	2DF		
		3	5DF	RST	3DF	2DF		
		4	JOG	MBS	DOWN	UP		
		5	JOG	RST	DOWN	UP		
		6	5DF	MBS	DOWN	UP		
		7	5DF	RST	DOWN	UP		
Cd60	V/F Frequency FC	0.5-240HZ					20	188
Cd61	PWM Frequency	0: 2k 1: 4k 2: 6k 3: 8k 4: 10k					2	189
Cd62	PWM Frequency2	15~40					30	190
Cd64	Dynamic braking mode	0~1					1	192
Cd65	Instant initial field time	Instant initial field time when start motor.					00~20.00	193
Cd66	Analog input filter time	4-64					32	194
Cd67	DC Bus fine tune	Adjust the standard score of DC Bus					± 15.0	195
Cd68	Dead Time compensation adjustment	0~10					10	196
Cd70	Dynamic Braking active level	120~140%					130	198
Cd71	Over Voltage prevention function active point	130~150%					140	199
Cd77	Kwh, Mwh memory clear	1: clear					0	X

Function Code Table

Code No.	Function	Detail of Data	Initial factory setting	MODBUS Address
Cd79	Auto saving function setting	0: Disable 1: Enable	1	X
Cd80	Modbus Protocol and communication mode setting	0: De-active 1: Active with RTU mode, only for monitoring.(8,n,1) 2: Active with RTU mode, change general parameter.(8,n,1) 3: Active with RTU mode, change of general parameter. Operational command by remote control.(8,n,1)	3	208
Cd81	RS485 communication address setting	1 240	1	209
Cd82	Series communication baud rate setting	0:2400 bps 1:4800 bps 2:9600 bps	2	210
Cd83	Series communication response time setting	0 15	0	211
Cd84	Series Communication broadcasting function setting	0:Active group broadcasting, de-active global broadcasting. 1:De-active both group and global broadcasting.	0	X
Cd85	LCD Display Setting	Cd85=0 Display 2 parameter in LCD Cd85=1 Display 4 parameter in LCD Cd85=2 Display 8 parameter in LCD	0	X
Cd87	Display Group of LCD monitor	Setting 0~3	0	X

Function Code Table

Code No.	Function	Detail of Data	Initial factory setting	MODBUS Address
CE00	Fault annunciation (The last)	D1-29	nOnE	X
CE01	Fault annunciation (Before the last)	D1-30	nOnE	X
CE02	Fault annunciation (The 2 nd before the last)	D1-31	nOnE	X
CE03	Fault annunciation (The 3 rd before the last)	D1-32	nOnE	X
CE04	Reserved		0	X
CE05	1 st step speed setting	0 240Hz	0	233
CE06	2 nd step speed setting	0 240Hz	0	234
CE07	3 rd step speed setting	0 240Hz	0	235
CE08	4 th step speed setting	0 240Hz	0	236
CE09	5 th step speed setting	0 240Hz	0	237
CE10	6 th step speed setting	0 240Hz	0	238
CE11	7 th step speed setting	0 240Hz	0	239
CE12	8 th step speed setting	0 240Hz	0	240
CE13	9 th step speed setting	0 240Hz	0	241
CE14	10 th step speed setting	0 240Hz	0	242
CE15	11 th step speed setting	0 240Hz	0	243
CE16	12 th step speed setting	0 240Hz	0	244
CE17	13 th step speed setting	0 240Hz	0	245
CE18	14 th step speed setting	0 240Hz	0	246
CE19	15 th step speed setting	0 240Hz	0	247
CE20	16 th step speed setting	0 240Hz	0	248
CE21	1 st step time setting	0 100Min	0	249

Function Code Table

Code No.	Function	Detail of Data	Initial factory setting	MODBUS Address
CE22	2 nd step time setting	0 100Min	0	250
CE23	3 rd step time setting	0 100Min	0	251
CE24	4 th step time setting	0 100Min	0	252
CE25	5 th step time setting	0 100Min	0	253
CE26	6 th step time setting	0 100Min	0	254
CE27	7 th step time setting	0 100Min	0	255
CE28	8 th step time setting	0 100Min	0	256
CE29	9 th step time setting	0 100Min	0	257
CE30	10 th step time setting	0 100Min	0	258
CE31	11 th step time setting	0 100Min	0	259
CE32	12 th step time setting	0 100Min	0	260
CE33	13 th step time setting	0 100Min	0	261
CE34	14 th step time setting	0 100Min	0	262
CE35	15 th step time setting	0 100Min	0	263
CE36	16 th step time setting	0 100Min	0	264
CE37	1st frequency increase setting	0~10.0%	0	265
CE38	2nd frequency increase setting	0~10.0%	0	266
CE39	3rd frequency increase setting	0~10.0%	0	267
CE40	Setting Times of 1st frequency increase	0~200 min	0	268
CE41	Setting Times of 2nd frequency increase	0~200 min	0	269
CE42	1st frequency decrease setting	0~10.0%	0	270
CE43	2nd frequency decrease setting	0~10.0%	0	271

Function Code Table

Code No.	Function	Detail of Data	Initial factory setting	MODBUS Address
CE44	3rd frequency decrease setting	0~10.0%	0	272
CE45	Setting Times of 1st frequency decrease	0~200 min	0	273
CE46	Setting Times of 2nd frequency decrease	0~200 min	0	274
CE47	Multi-step function mode selection	0 3	0	275
CE48	Multi steps function operation reset	0 1	0	X
CE49	Multi steps process control continuous operation	0 2	0	277
CE50	Multi-step function time error adjust	0 256	100	X
CE52	Choice of multi-speed record file	1 6	1	X
CE53	Multi-steps all files set to default	0 1	0	X
CE54	Multi-steps memory duplicate function	1 6	0	X
CE55	Yards counter clear	0~1	0	X
CE56	Stall prevention selection during acceleration	0: Invalid 1: Valid	0~1	284
CE57	Stall prevention level during acceleration	Set rated current as 100% for stall preventive leveling acceleration	30~200	285
CE58	Stall prevention limit during acceleration	In accordance with Cd70 setting value when inverter operation is over motor rated frequency to reduce stall prevention limit during acceleration	30~100	286
CE59	Stall prevention limit during deceleration	0: Invalid 1: Valid	0~1	287

Function Code Table

Code No.	Function	Detail of Data	Initial factory setting	MODBUS Address
CE61	Stall prevention selection during constant speed operation	0: Invalid 1: Decelerate by deceleration time 2 (Cd11)	0~1	289
CE62	Stall prevention level during constant speed operation	Set rated current as 100% for constant speed stall preventive level	30~ 200	290
CE63	Low voltage prevention active point	Set input voltage (RST)	155~ 500	291
CE64	Speed search current	When Cd28=2 is valid (please reduce setting value when unable to restart)	0~ 200	292
CE65	Speed search deceleration time	When Cd28=2 is valid	0.1~ 10.0	293
CE66	Speed search waiting time	When Cd28=2 is valid	0.0~ 20.0	294
CE67	Momentary power loss direction	0: Invalid 1: Valid, restart when power recovered in time of (Cd80), detect low voltage of master power when exceeded. 2: Movement of CPU is valid, restart when power recovered (Cd80 will not be considered)	0~2	295
CE68	Momentary power loss compensation time	Restart valid time limit when set Cd79=1	0~2.0	296
CE69	Voltage recovery time	From 0V to recover is time of maximum output voltage when set restart	0.1~ 20.0	297
CE70	Inverter overheating forecast detection level	Set Cd84 as 100% for level of detecting overheating forecast for inverter	50~ 100	298
CE71	Active when inverter overheating forecast detection	0: Deceleration stop 1: Coast stop 2: Emergency stop 3: Continuous operation	0~3	299
CE72	Temperature protection level	Set 50 as unit for detecting level of inverter overheating Software protection is invalid when set 130 (OH is only hardware protection)	50~ 130	300

Function Code Table

Code No.	Function	Detail of Data	Initial factory setting	MODBUS Address
CE73	Current arrearage range	Set hysteresis range when relay (Cd47、 Cd48)and DO (Cd49) current detected	2~20	301
CE74	Current detect level	Set current detect level when current detected	30~150	302

12. Modbus Address of Display Data

Description	Notes	Range	Unit	MODBUS Address
Operation frequency		0 24000	0.01HZ	328
Current feedback		0 9999	0.1A	329
Operation command		0 24000	0.01HZ	330
DC voltage		0 9999	0.1V	331
Output voltage	$V_{ac} = \text{Output voltage} / \sqrt{2}$	0 9999	0.1	332
External terminal mode		0 255		333
Module Temperature		112 1130	0.1	334
Operation status	Bit2: 0=Stop, 1=RUN Bit14: 0=FR, 1=RR			335
Operation command	MASTER changes: Bit0: FWD command Bit1: REV command Clear Bit0 Bit1: Stop command Bit2: Reset after failure command			336
Failure	Bit 4,3,2,1,0 = 10:OH 0:None 12:OL 4:OCPA 14:OC 5:OCPd 15:PLU 6:OCPn 16:OL2 8:OV 17:BuOH			337
Power factor		0~100	0.01	338
Instant power		0~65535	0.01KW	339
KW-H		0~9999	0.01KW H	340
MW-H		0~65535	0.1MWH	341
Current time of multi-step function		0~999	1min	342
Yards counter's low 8bits & Current step of multi-step function	0~7 bit: Current step of multi-step function	0 16	1step	343
	8~15 bit : Yards counter's low 8bits	0 255	0.01 yard	
Yards counter's high 16bits		0 65535	2.56 yard	344

13. Serial Communications User Manual

This product built in with standard RS422/RS485 communicate port, support international standard MODBUS protocol, user can monitor single or many inverters by using PLC, PC, industrial computer or other equipment which support MODBUS protocol

A. The physical link

The wiring of this product can use either RS422(4 wires) or RS485(2wires).

RS422

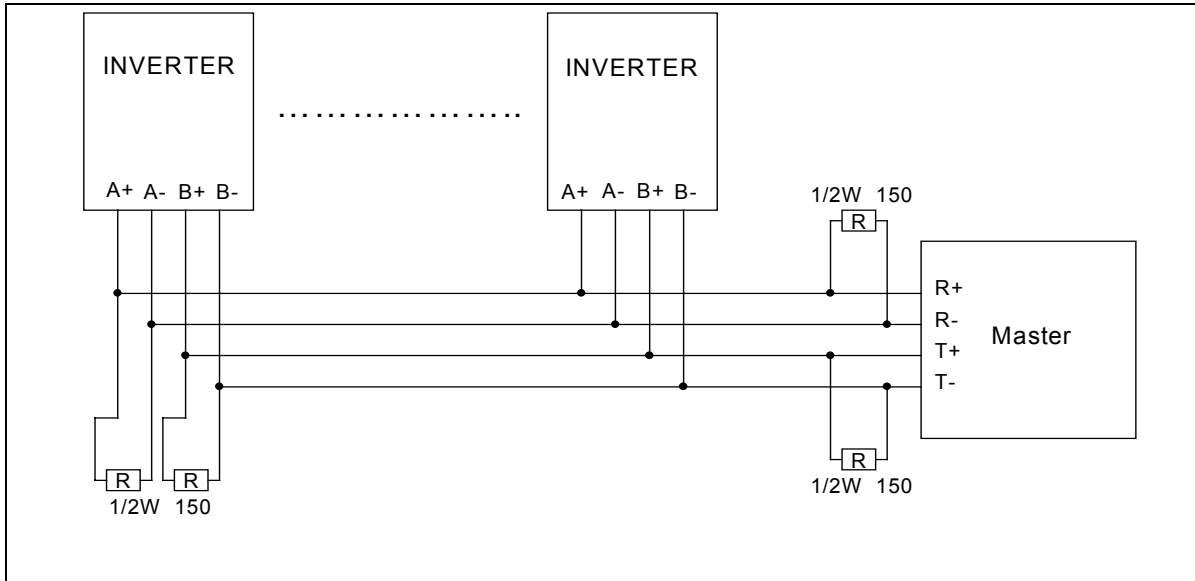


Fig 13-1

RS485

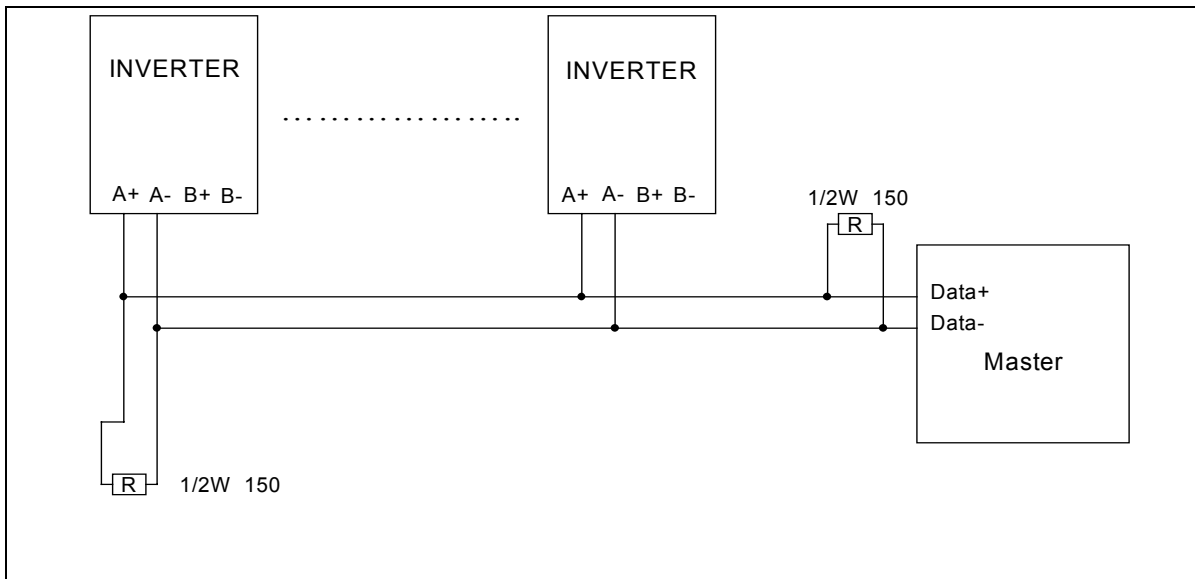


Fig13-2

Note :

- a. When use REMOTE Keyboard and second set RS485 at the same time , please notice that external terminal Vout will be disabled.
- b. When use RS422 (4wires), The 'REMOTE' socket cannot connect to any device.
- c. Single transaction can read up to 10 continuous data from slave device.
- d. It can connect up to 32 devices in single net.
- e. The R in wiring diagram is terminal resister, only used on the device in the end of communication line.

B. Data structure in communication

This product support MODBUS RTU and MODBUS ASCII protocol. In ASCII mode, every byte of the data will transfer to two ASCII code. Ex. If byte data is 63H, it will be 36H, 33H in ASCII code.

(1) Hex to ASCII code transfer table

Char	' 0 '	' 1 '	' 2 '	' 3 '	' 4 '	' 5 '	' 6 '	' 7 '
ASCII code	30H	31H	32H	33H	34H	35H	36H	37H

Char	' 8 '	' 9 '	' A '	' B '	' C '	' D '	' E '	' F '
ASCII code	38H	39H	41H	42H	43H	44H	45H	46H

Char	' : '	CR	LF					
ASCII code	3AH	0DH	0AH					

Serial Communications User Manual

C. Function code

This product support Function code 03H and 06H in MODBUS protocol.

(1) Function 03H : Read holding register

Read the binary contents of holding registers (4 x references) in the slave.
Broadcast is not supported. The maximum parameters supported by various controller models are listed on page.

Ex: Read data from 3 continuous addresses in register. The beginning address is 0080H, the data frame are listed as follow.

Query

Field Name	Example (hex)	ASCII code	RTU 8-Bit Field
Header		':' (colon)	None
Slave Address	F0	F 0	1111 0110
Function	03	0 3	0000 0011
Start Address Hi	00	0 0	0000 0000
Start Address Lo	80	8 0	1000 0000
No. of Register Hi	00	0 0	0000 0000
No. of Register Lo	03	0 3	0000 0011
Error Check		LRC (2 chars)	CRC (16 bits)
Trailer		CR LF	None
Total Bytes		17	8

Response

Field Name	Example (hex)	ASCII code	RTU 8-Bit Field
Header		':' (colon)	None
Slave Address	F0	F 0	1111 0000
Function	03	0 3	0000 0011
Byte Count	06	0 6	0000 0110
1 st Data Hi	03	0 3	0000 0011
1 st Data Lo	E8	E 8	1110 1000
2 nd Data Hi	00	0 0	0000 0000
2 nd Data Lo	07	0 7	0000 0111
3 rd Data Hi	00	0 0	0000 0000
3 rd Data Lo	00	0 0	0000 0000
Error Check		LRC (2 chars)	CRC (16 bits)
Trailer		CR LF	None
Total Bytes		23	11

(2) Function 06H : preset signal register

Presets a value into a single holding register (4 x reference). When broadcast, the function presets the same register reference in all attached slaves. The maximum parameters supported by various controller models are listed on page.

Ex. To inverter in F0H address protocol, pre set data 6000(1770H) into 0080H register, the protocol frame will listed as below.

Query

Field Name	Example (hex)	ASCII code	RTU 8-Bit Field
Header		':' (colon)	None
Slave Address	F0	F 0	1111 0110
Function	06	0 6	0000 0110
Register Address Hi	00	0 0	0000 0000
Register Address Lo	80	8 0	1000 0000
Preset Data Hi	17	1 7	0001 0111
Preset Data Lo	70	7 0	0777 0000
Error Check		LRC (2 chars)	CRC (16 bits)
Trailer		CR LF	None
Total Bytes		17	8

Response

Field Name	Example (hex)	ASCII code	RTU 8-Bit Field
Header		':' (colon)	None
Slave Address	F0	F 0	1111 0110
Function	06	0 6	0000 0110
Register Address Hi	00	0 0	0000 0000
Register Address Lo	80	8 0	1000 0000
Preset Data Hi	17	1 7	0001 0111
Preset Data Lo	70	7 0	0777 0000
Error Check		LRC (2 chars)	CRC (16 bits)
Trailer		CR LF	None
Total Bytes		17	8

D. Error check Generation

(1) LRC Generation

Add all bytes in the message, excluding the starting colon and ending CRLF. Add them into an eight-bit field, so that carries will be discarded.

Subtract the final field value from FF hex (all 1's), to produce the ones complement. Add 1 to produce the two's-complement. Ex. The query data is F0H + 06H + 00H + 80H + 17H + 70H = FDH, the two's complement is 02H. The '0' & '2' will be the LRC.

(2) CRC Generation

Generating a CRC

- Step 1** Load a 16-bit register with FFFF hex (all 1's). Call this the CRC register.
- Step 2** Exclusive OR the first eight-bit byte of the message with the low order byte of the 16-bit CRC register, putting the result in the CRC register.
- Step 3** Shift the CRC register one bit to the right (toward the LSB), zero filling the MSB. Extract and examine the LSB.
- Step 4** If the LSB is 0, repeat Step 3 (another shift). If the LSB is 1, Exclusive OR the CRC register with the polynomial value A001 hex (1010 0000 0000 0001).
- Step 5** Repeat Steps 3 and 4 until eight shifts have been performed. When this is done, a complete eight-bit byte will have been processed.
- Step 6** Repeat Steps 2 ... 5 for the next eight-bit byte of the message. Continue doing this until all bytes have been processed.
The final contents of the CRC register is the CRC value.
- Step 7** When the CRC is placed into the message, its upper and lower bytes must be swapped as described below.

Pseudo code for generating a CRC-16 :

```
CONST ARRAY BUFFER          /* data, ex: F0h, 06h, 00h, 80h, 17h, 70h */
CONST WORD POLYNOMIAL = 0A001h      /* X16 = X15 + X2 + X1 */
/* SUBROUTINE OF CRC CALCULATE START */
CRC_CAL(LENGTH)
VAR INTEGER LENGTH;
{  VAR WORD CRC16 = 0FFFFH;          /* CRC16 initial */
   VAR INTEGER = i,j;              /* LOOP COUNTER */
   VAR BYTE DATA;                 /* DATA BUFFER */
   FOR (i=1;i=LENGTH;i++)          /* BYTE LOOP */
   {  DATA == BUFFER[i];
      CRC16 == CRC16 XOR DATA
      FOR (j=1;j=8;J++)             /* BIT LOOP */
      {  IF (CRC16 AND 0001H) = 1 THEN
          CRC16 == (CRC16 SHR 1) XOR POLYNOMIAL;
        ELSE
          CRC16 == CRC16 SHR 1;
          DATA == DATA SHR 1;
      };
   };
};
RETURN(CRC16);
};
```

E. Group and Global Broadcast function

(1) Group Broadcast

User can use this function to control certain group of inverter at the same time. When master send out group address data, the slave inverters will react when receive order, but will not send any signal back to master.

(2) Global Broadcast

User can use this function to control all inverters at the same time. When master global broadcast, all slaves inverters will react after receive order, but will not send any signal back to master.

Group and Global broadcast address should be recognized refer to table as below, when the group and global broadcast address is in use.

There are 240 addresses in total for inverter setting, which means it can connect up to 240 inverters at the same time, and provide 1 Global Broadcast address 15-group address. Each group address can control up to 16 inverters, and user can set it.

Group	Individual Address	Group address	Global address
Group1	1...16	241	0
Group 2	17...32	242	0
Group 3	33...48	243	0
Group 4	49...64	244	0
Group 5	65...80	245	0
Group 6	81...96	246	0
Group 7	97...112	247	0
Group 8	113...128	248	0
Group 9	129...144	249	0
Group 10	145...160	250	0
Group 11	161...176	251	0
Group 12	177...192	252	0
Group 13	193...208	253	0
Group 14	209...224	254	0
Group 15	225...240	255	0